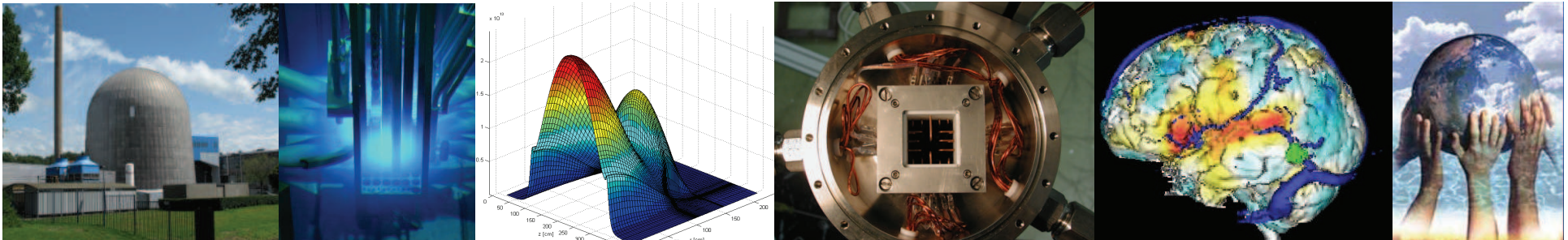


Multi-Physics Simulation of Molten Salt Reactors

Danny Lathouwers
Delft University of Technology
Dept. of Radiation Science and Technology

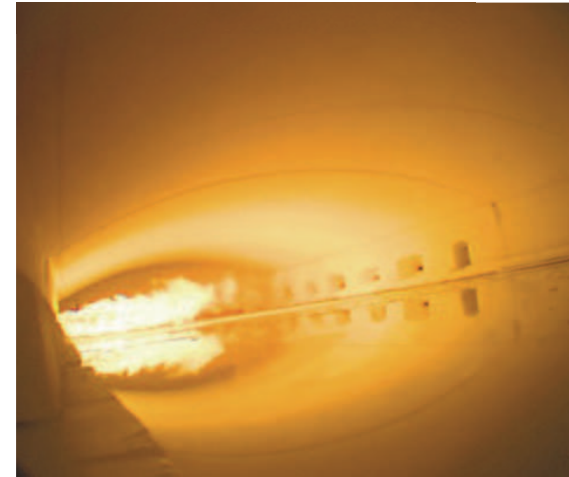
Co-workers: Michiel Hoogmoed, Jan Leen Kloosterman,
Dion Koeze, Carlo Fiorina, Lodewijk Frima, Joseph
Kophazi, Erik van der Linden, Marco Tiberger, ...



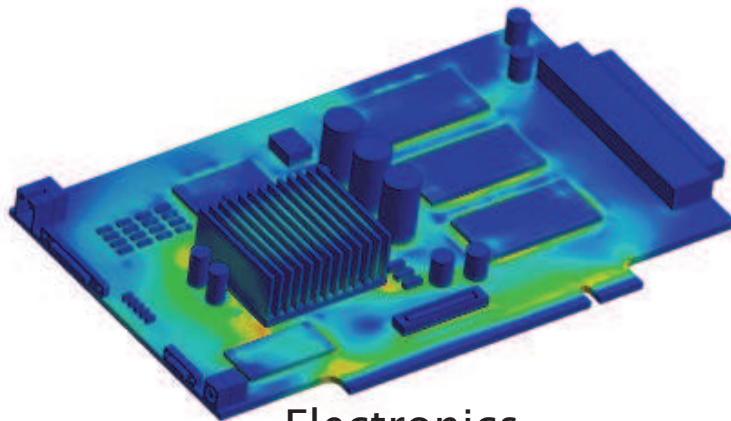
Multiphysics in various fields



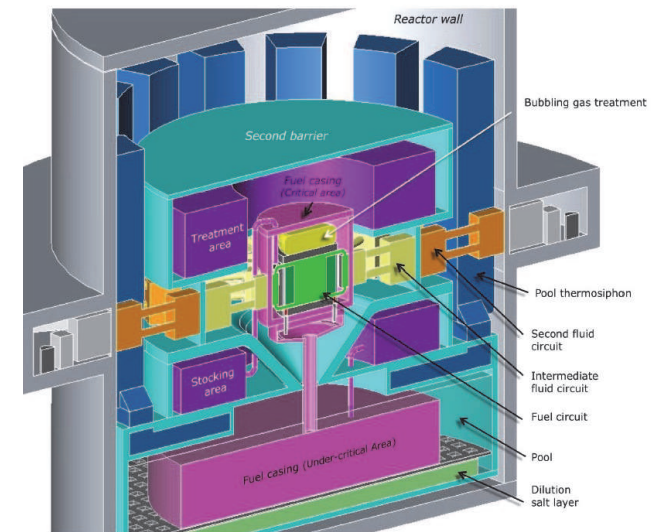
Fluid-structure interaction



Furnace (thermal, chemistry)

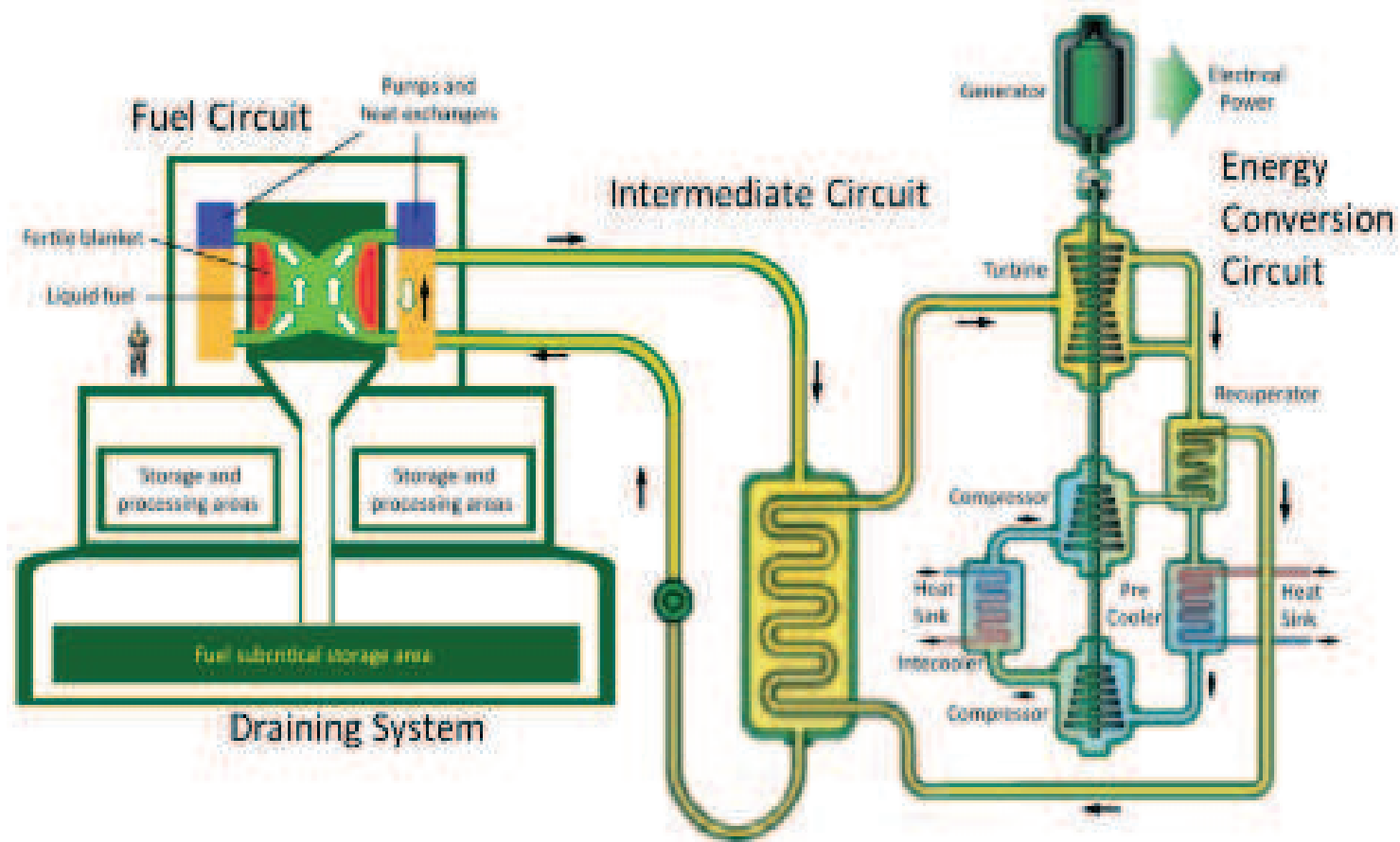


Electronics
(thermal, stress analysis)



Nuclear (flow, thermal,
stress, radiation)

MSFR



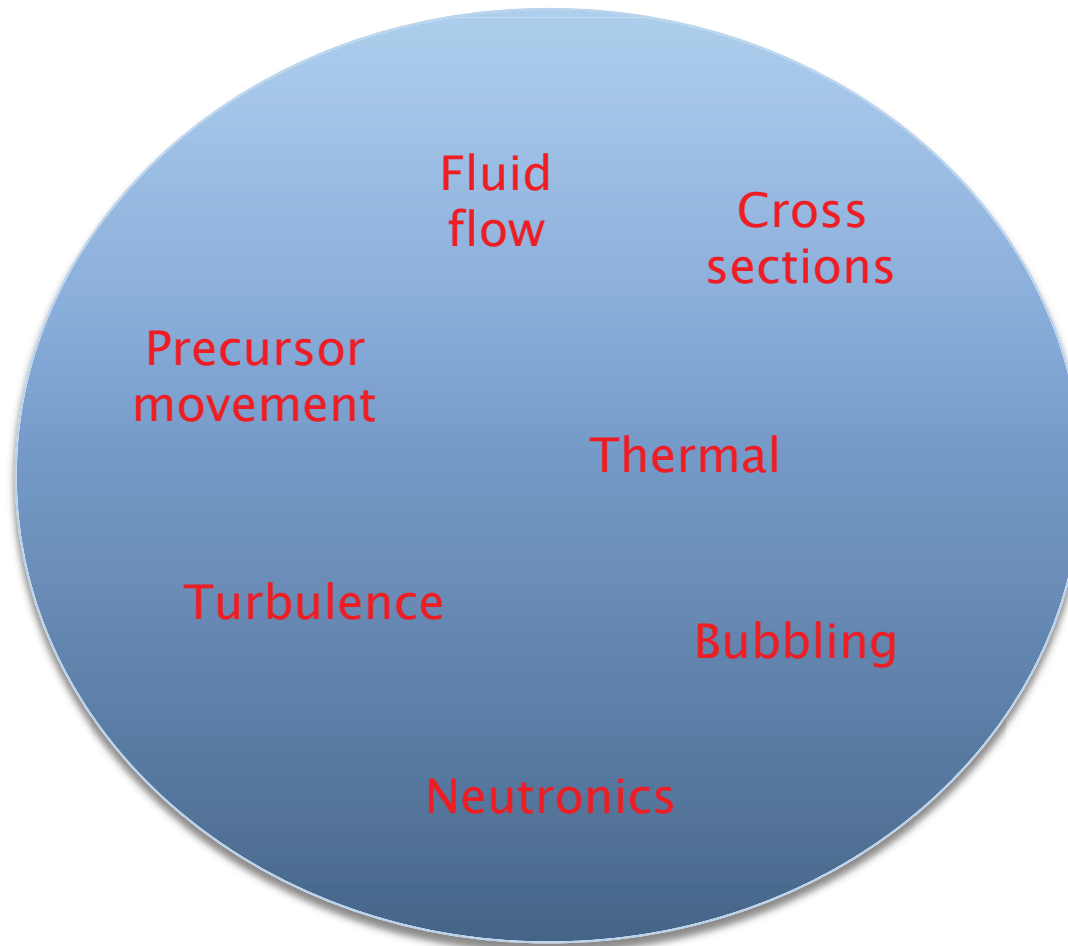
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Main topics discussed

- ▶ Physics involved: time-scales, complexity
- ▶ Coupling strategies (pro/cons)
- ▶ MSRE application
- ▶ MSFR application
- ▶ Concluding remarks



Multiphysics in the MS(F)R

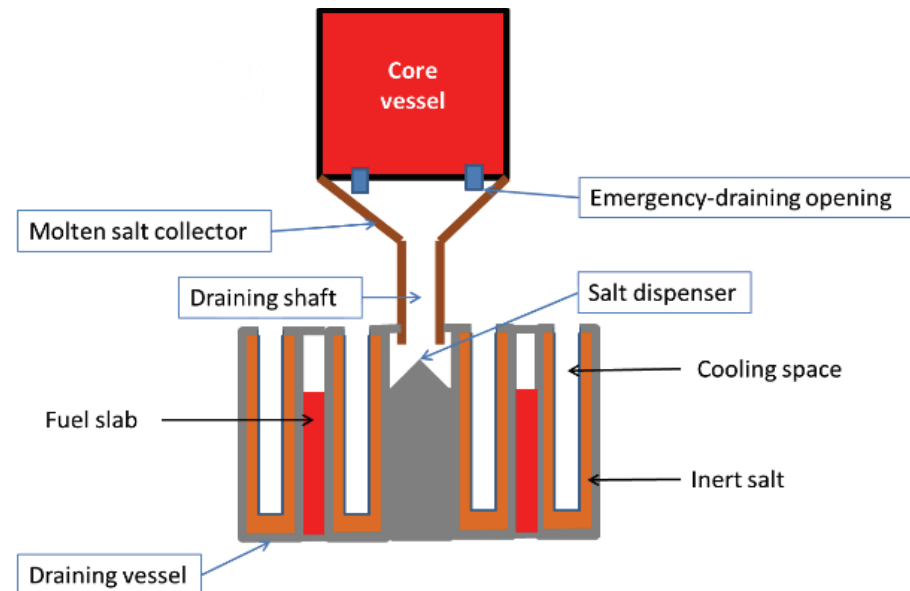
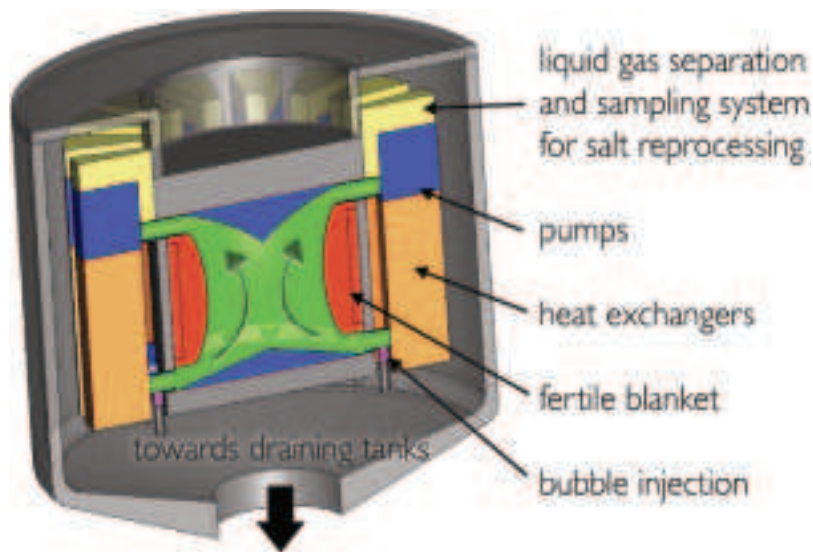


► Capabilities needed

- Moving fuel \rightarrow moving precursors
- Complex geometry
- Three-dimensionality
- Heat transfer, (two-phase) fluid flow, stress analysis, neutronics
- Temperature feedback effects on cross sections
- Voidage feedback from bubbling and on effect flow structure

Relevant transients

- ▶ Two types of transients are considered
 - Fuel circuit transients
 - Transients involving the emergency draining tank



► Main transients chosen

Code	Class	Transient	Initiating event / description
1.1.a	1 – Fuel Circuit	ULOHS	a) Reduction of the mass flow rate in the intermediate circuit
1.2.a	1 – Fuel Circuit	ULOFF	a) Fuel circuit pump failure
1.3.	1 – Fuel Circuit	TLOP	Phase 0 and phase 2
1.4.a	1 – Fuel Circuit	OVC	a) Increase in the fuel salt flow
1.4.c		OVC	c) Decrease of temperature in the intermediate circuit
1.6.a	1 – Fuel Circuit	RAA	a) Increase/decrease of salt (fissile) volume in the core cavity or heterogeneity of fissile salt (positive/negative reactivity insertion)
2.1.a	2 – EDS	EDS-LOHS	a) Insufficient cooling circuit flow
2.3	2 – EDS	EDS-BA	Blockage of fuel salt



Neutronics Modeling

Consider full transport model as example

$$\frac{1}{v} \frac{\partial \varphi_g}{\partial t} + \hat{\Omega} \cdot \nabla \varphi_g + \Sigma_{t,g} \varphi_g = \sum_{g'} \int_{4\pi} \Sigma_{s,g' \rightarrow g}(\hat{\Omega}' \rightarrow \hat{\Omega}) \varphi_{g'} d\hat{\Omega}' + \frac{\chi_g}{4\pi k_{eff}} (1 - \beta) \sum_g v \Sigma_{f,g} \int_{4\pi} \varphi_g d\hat{\Omega} + \sum_i \lambda_i C_i$$
$$\frac{\partial C_i}{\partial t} + \lambda_i C_i + \boxed{\nabla \cdot \vec{u} C_i} = \beta_i \sum_g v \Sigma_{f,g} \int_{4\pi} \varphi_g d\hat{\Omega}$$

Magnitude of the problem

- Mesh: 10000 elements
- Angle: 24 in practice for MSR
- 8 precursors
- Space: Linear polynomials \rightarrow 4 basis functions
- Energy: pm 10 groups

➡ No dof: pm 10 Million (+ time stepping)

Diffusion is a (much) cheaper alternative



Neutronics time scales

Time scales relevant to the neutronics part of the problem

- Prompt time scale $\tau = \frac{\Lambda}{\beta - \rho} < 1ms$
- Reactor period $\tau = \frac{1}{\rho} \sum_i \frac{\beta_i}{\lambda_i} \gg 1s$

Wide range of time scales

- ▶ Usually no need to resolve prompt time scale
- ▶ Most neutronics codes are **implicit** in time (or use Prompt Jump Approximation)

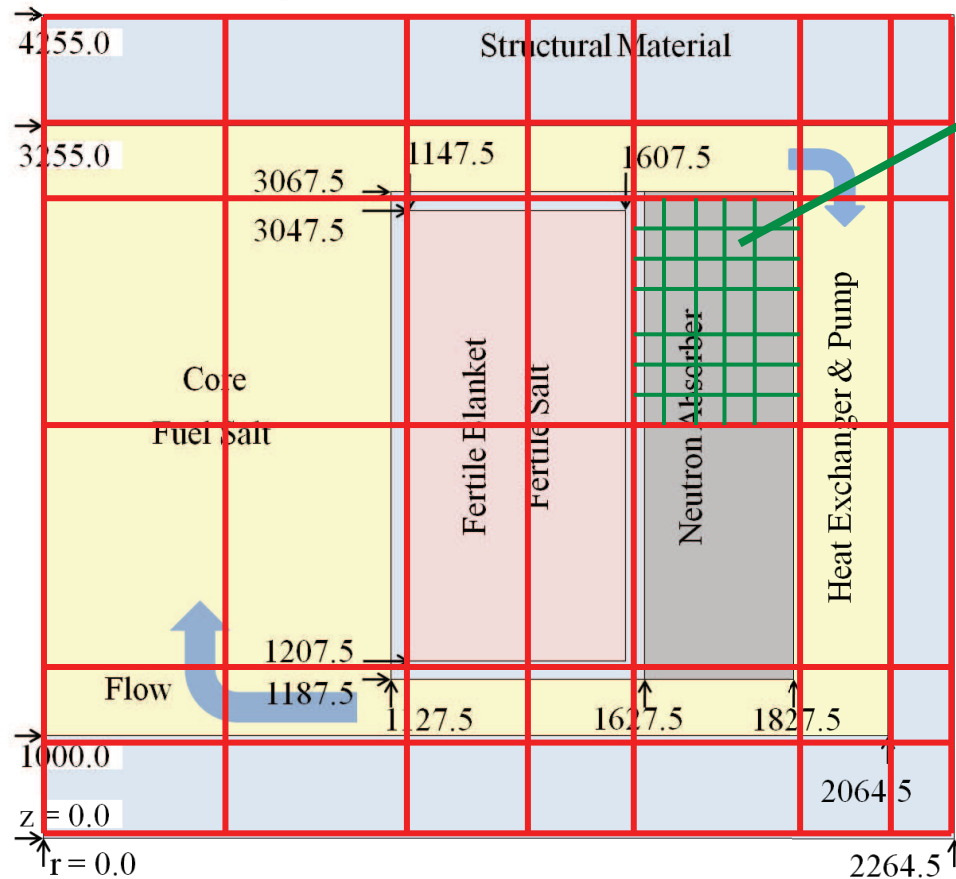


Cross section processing

- ▶ Cross sections depend on space and time through temperature and composition
- ▶ Mapping needed of the system select proper xs set (in practice 20–1000 sets are used)
- ▶ Each mesh element corresponds to specific material
- ▶ Libraries need to be generated (Scale, Serpent, etc). Around 10 groups sufficient for MSFR
- ▶ XS need to be interpolated wrt temperature (either for each cell or for each material region using an average T)
- ▶ Density dependence as well (bubbling)
- ▶ XS generation somewhat of an art



Cross section mapping and interpolation



Segmentation
of the domain

Element associated with
region X, having
temperature $T=750K$

Interpolate XS files
for region X

Lib_X_500

$T_1 = 500K$

Lib_X_700

$T_1 = 700K$

Lib_X_900

$T_1 = 900K$

$T_1 = 750K$

$$\Sigma_i = \frac{\rho}{\rho_{ref}} \left(\Sigma_{i,ref} + A_i \log \frac{T}{T_{ref}} \right)$$



Flow Modeling

MSFR: turbulent flow

Boussinesq approximation reasonable in most cases

$$\frac{\partial \rho \vec{u}}{\partial t} + \nabla \cdot \rho \vec{u} \vec{u} = -\nabla p + \nabla \cdot \vec{\tau}_{eff} - \rho \vec{g} \beta (T - T_{ref}) + S_u$$

$$\nabla \cdot \vec{u} = 0$$

$$\frac{\partial \rho h}{\partial t} + \nabla \cdot \rho \vec{u} h = \nabla \cdot \lambda_{eff} \nabla T + P$$

+Turbulence model

Magnitude of the problem

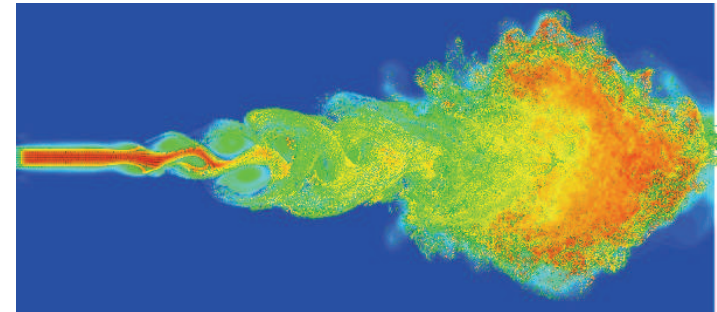
- Mesh: 40000 elements
- Space: Linear polynomials \rightarrow 4 basis functions
- 5 main flow variables + turbulence model
- No dof: pm 1 Million (+ time stepping)



Fluid flow time scales

We deal with a turbulent flow with a large variety of spatial and time scales

- Large eddy turnover $\tau = \frac{L}{u} \sim 10s$
- Cascading (decay) $\tau = \frac{k}{\varepsilon} < 1s$
- Kolmogorov time scale $\tau = \left(\frac{\nu}{\varepsilon}\right)^{1/2} \ll 1s$



- ▶ We use RANS models where we do not resolve the small scale turbulence
- ▶ For stability reasons, turbulence production/dissipation terms usually handled implicitly

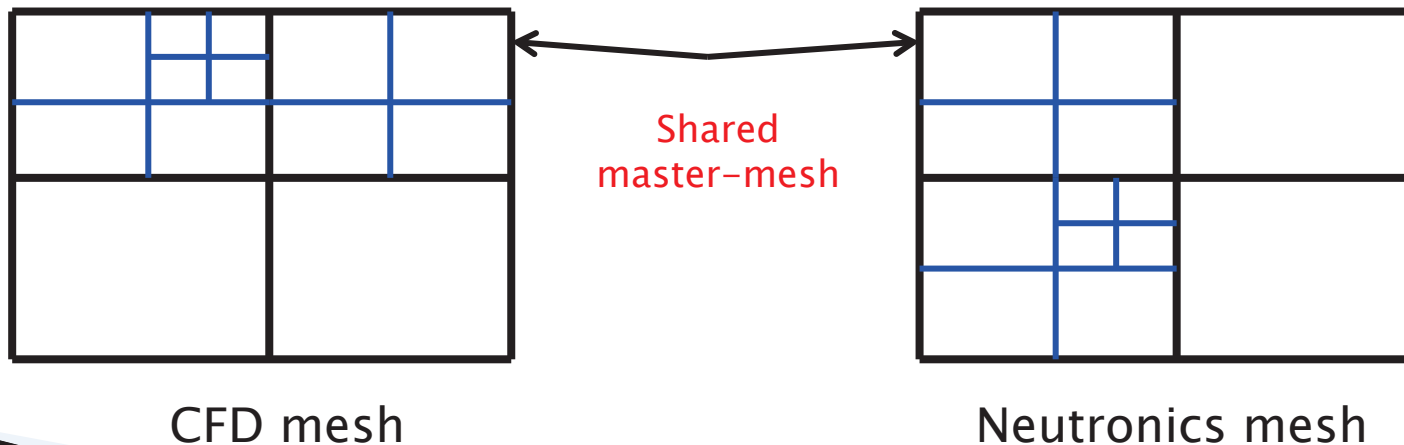
Data exchange

*Mesheres for each physics module not the same
=> interpolation required*

Important properties:

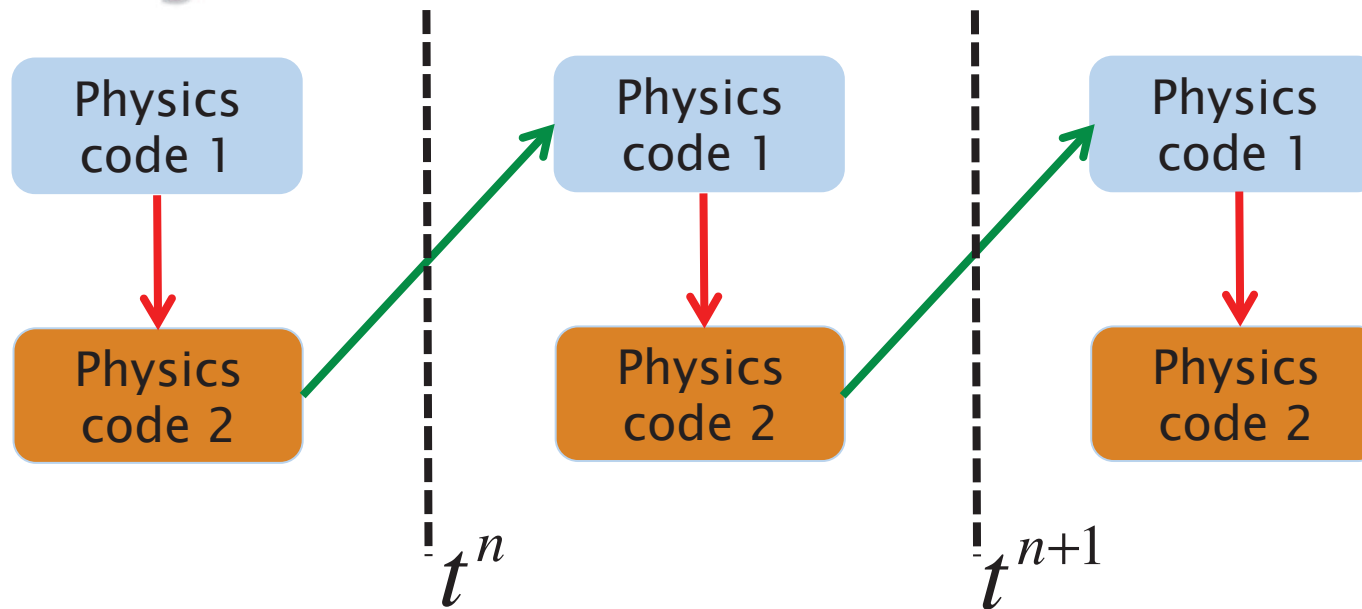
- ▶ Conservation
- ▶ Speed of interpolation

Hierarchical meshes combined with *Galerkin projection* satisfy both these properties.



Conventional (loose) coupling

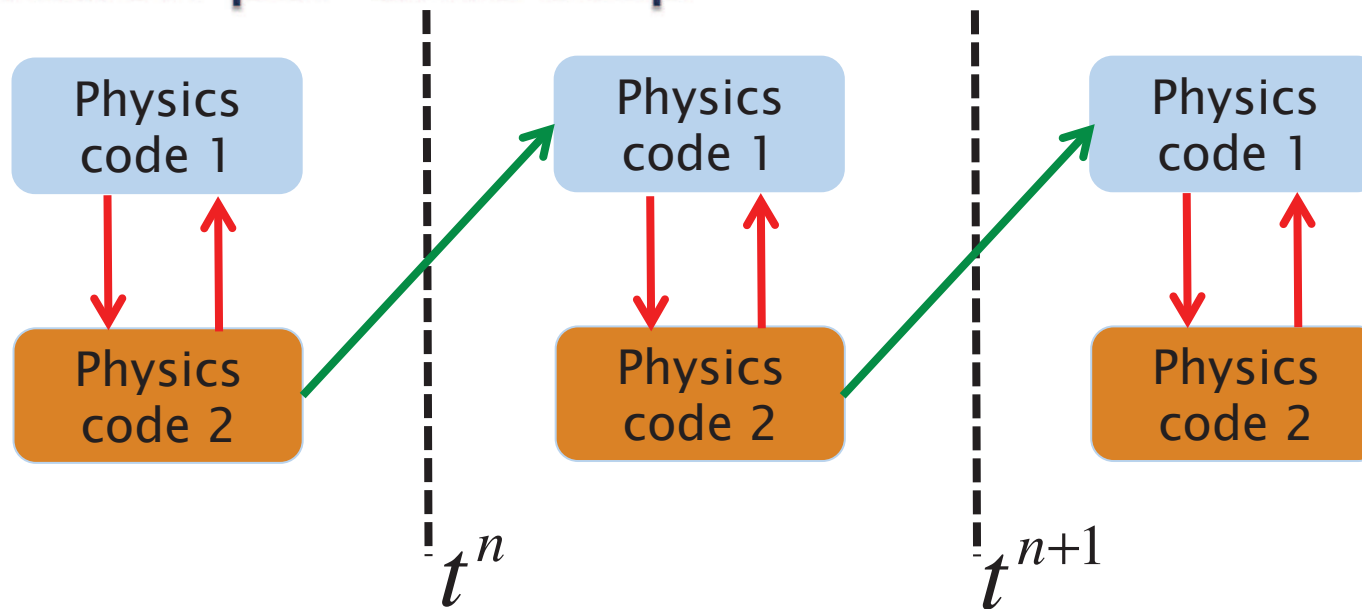
Splitting schemes



- ▶ Easy to implement using existing (black-box) codes
- ▶ Cheap on a time step basis
- ▶ At most first-order time accuracy
- ▶ Stability may be issue; though difficult to analyse
- ▶ Times at which to data needs exchange depends on physics and time scales

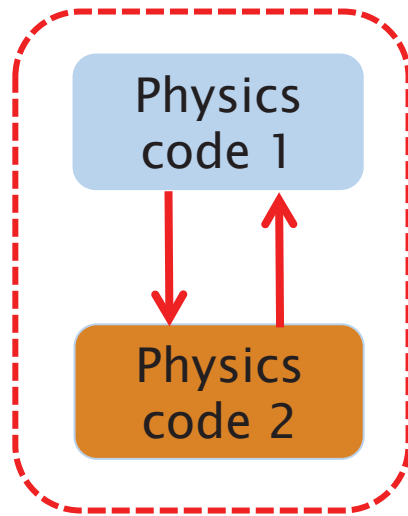
Tight coupling scheme

Iteration per time step



- ▶ Still easy to implement using existing codes
- ▶ Iteration may be expensive
- ▶ Time accuracy dictated by that of the individual codes (full potential can be achieved)
- ▶ Coupling no longer dominates stability

Towards improved efficiency



- ▶ *Sequential exchange of data* between codes is formally a **Picard (fixed-point) iteration**

$$u - f(u) = 0 \rightarrow u^{k+1} = f(u^k)$$

- ▶ Convergence in general is slow (linear)
- ▶ Easy to do (and often done!)

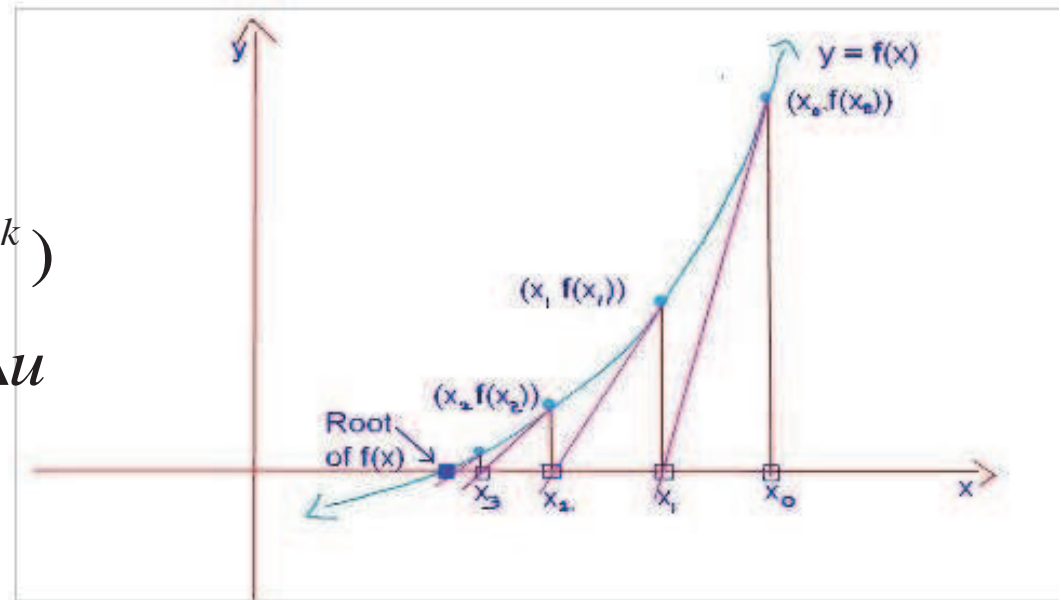
Variations

- Anderson acceleration: keeps a series of iterates and finds optimal combination
- Aitken acceleration: Keeps 3 iterates and combines to new
- ...



Newton's method

$$F(u) = 0 \rightarrow \begin{cases} \mathbf{J} \Delta u = -F(u^k) \\ u^{k+1} = u^k + \Delta u \end{cases}$$



- ▶ Quadratic convergence close to solution
- ▶ Requires *Jacobian* (intrusive!), mostly unavailable)
- ▶ Large linear system in each Newton iteration

Jacobian-Free Newton Krylov (JFNK)

(D. Knoll etc)

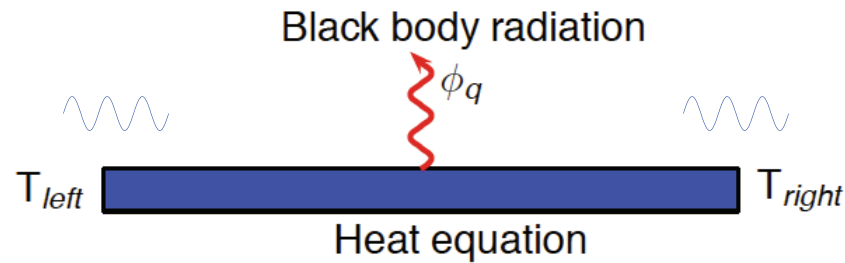
- ▶ Innovative idea combining:
 - Newton iteration for the non-linearity
 - Krylov method for the linear system in each step
 - A smart trick
- ▶ BUT: How possible without Jacobian?
- ▶ Krylov methods require matrix multiplication only: Jv

$$Jv \simeq \frac{F(u + \varepsilon v) - F(u)}{\varepsilon}$$

- ▶ JFNK only requires residual F
- ▶ Preconditioning for efficient Krylov is essential (usually Gauss-Seidel is used: physics preconditioning)

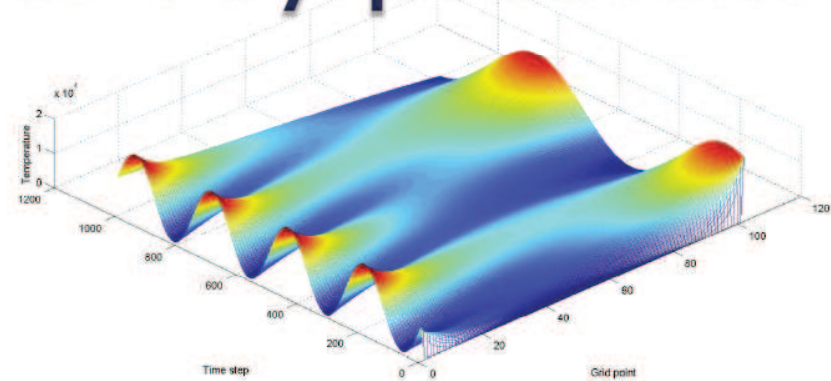


Coupling example: Toy problem

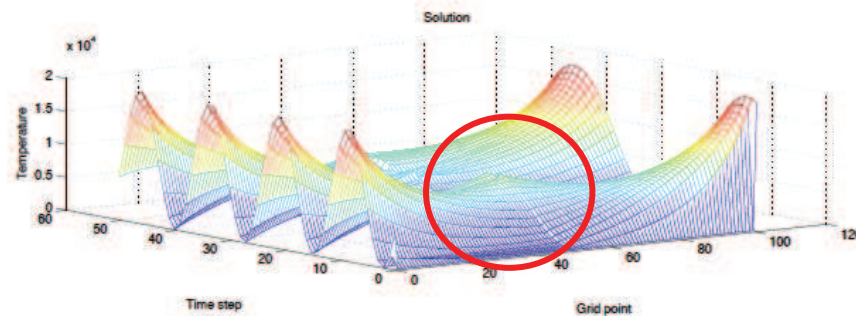


Physics 1: left half

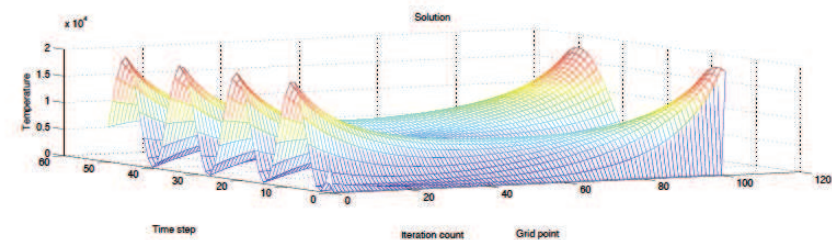
Physics 2: right half



'Exact' solution

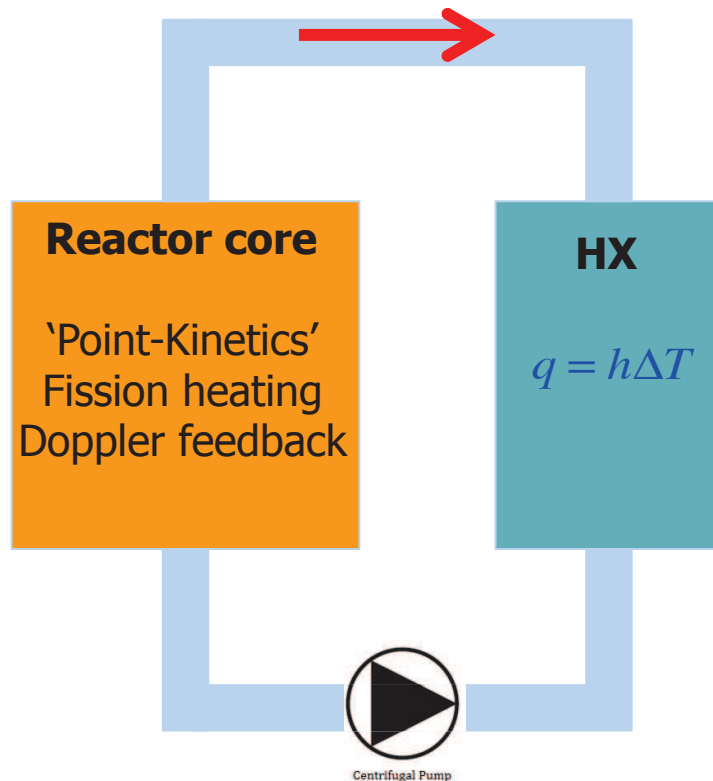


Traditional coupling
artifacts near coupling location

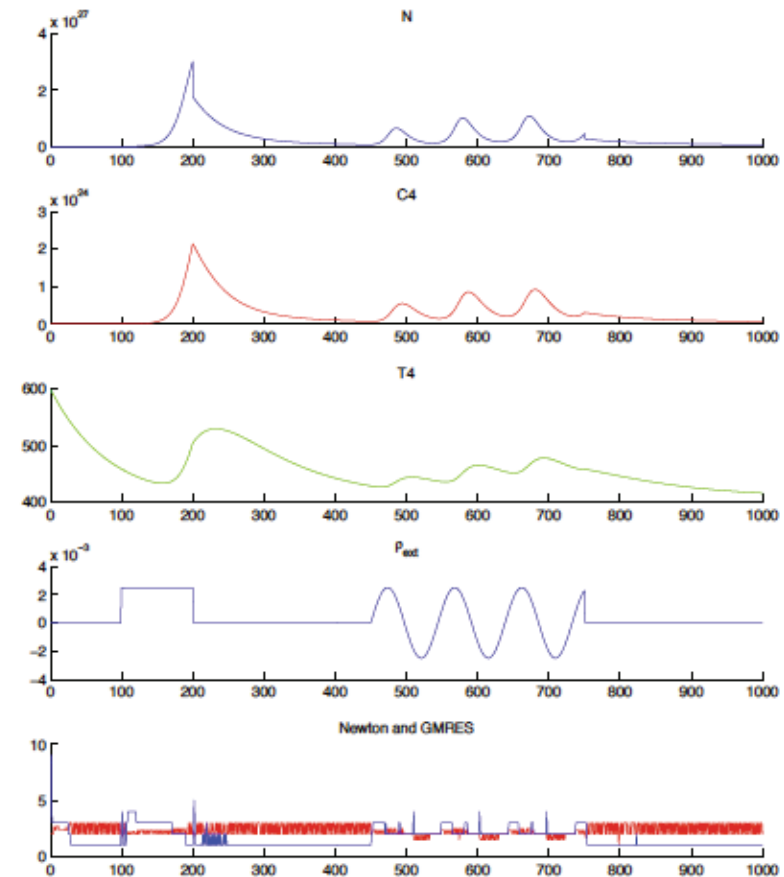


JFNK

Coupling example: MSR-loop

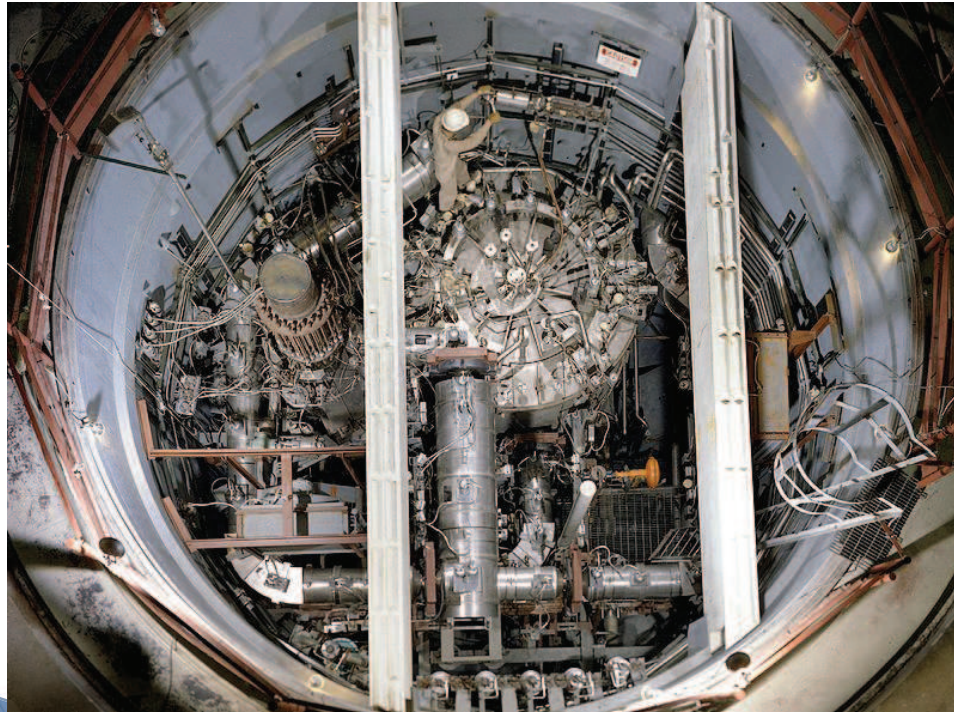


External reactivity transient



- ▶ JFNK stable and efficient
- ▶ Relatively easy problem (1–2 Newton steps)
- ▶ Some hick-ups when using large external reactivity with (too) large time-steps

Molten Salt Reactor Experiment



SAMOFAR

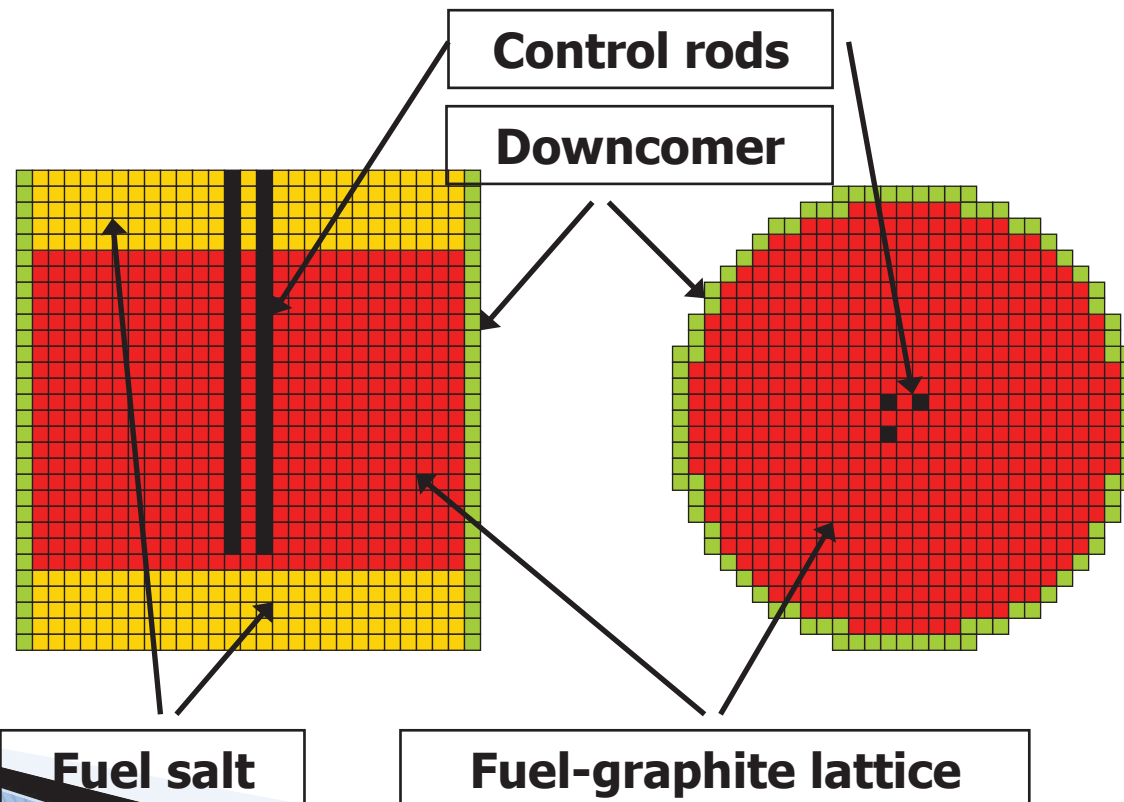
Molten Salt Reactor Experiment

- ▶ Developing calculation scheme for MSR
 - 3D
 - time-dependent
 - feedback by coupling neutronics and thermal calculations
 - Model the MSRE
 - Keep programs general
- ▶ Assumptions
 - Fuel velocity field is input
 - Flow parallel to the axis of the core



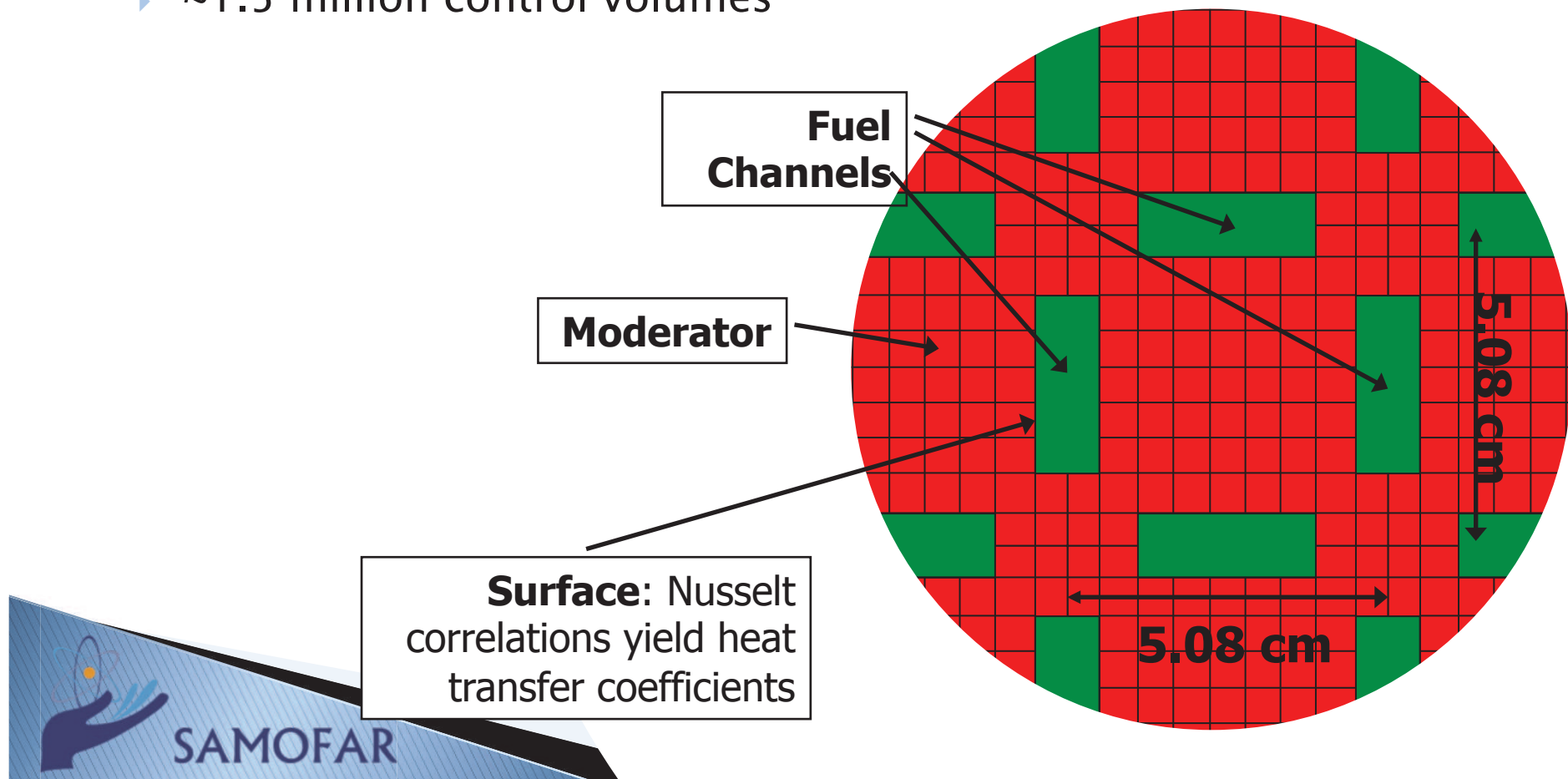
MSRE: 3D model

- ▶ Approximating cylindrical reactor in X-Y-Z geometry
- ▶ 8 group cross section library by SCALE
- ▶ Internal albedo boundaries for control rods



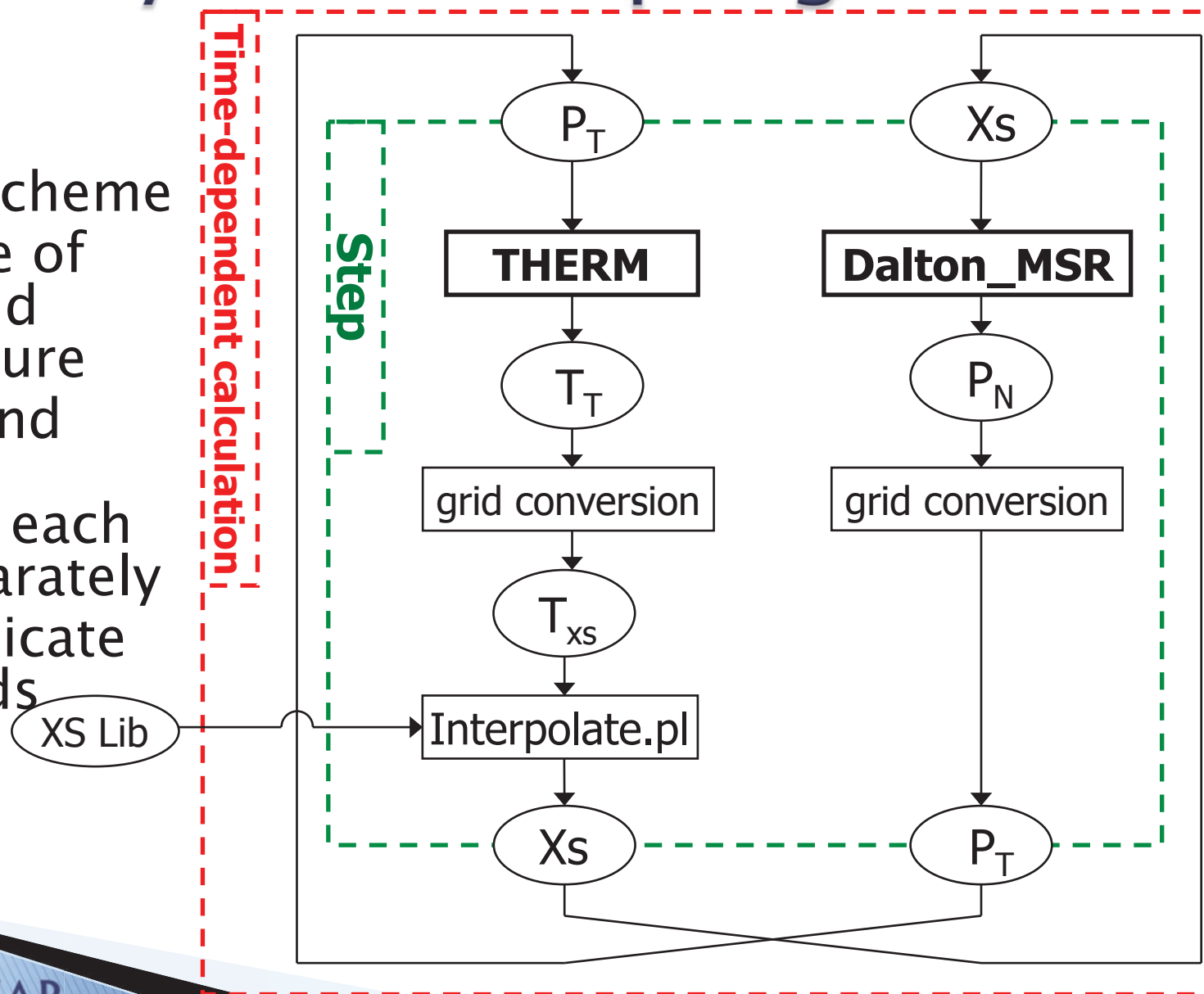
MSRE: 3D model

- ▶ Fuel: Heat convection (vertical)
- ▶ Moderator: Heat conduction (3D)
- ▶ Individually calculating each fuel channel (1150 channels)
- ▶ Bulk temperatures for fuel channels
- ▶ ~1.5 million control volumes



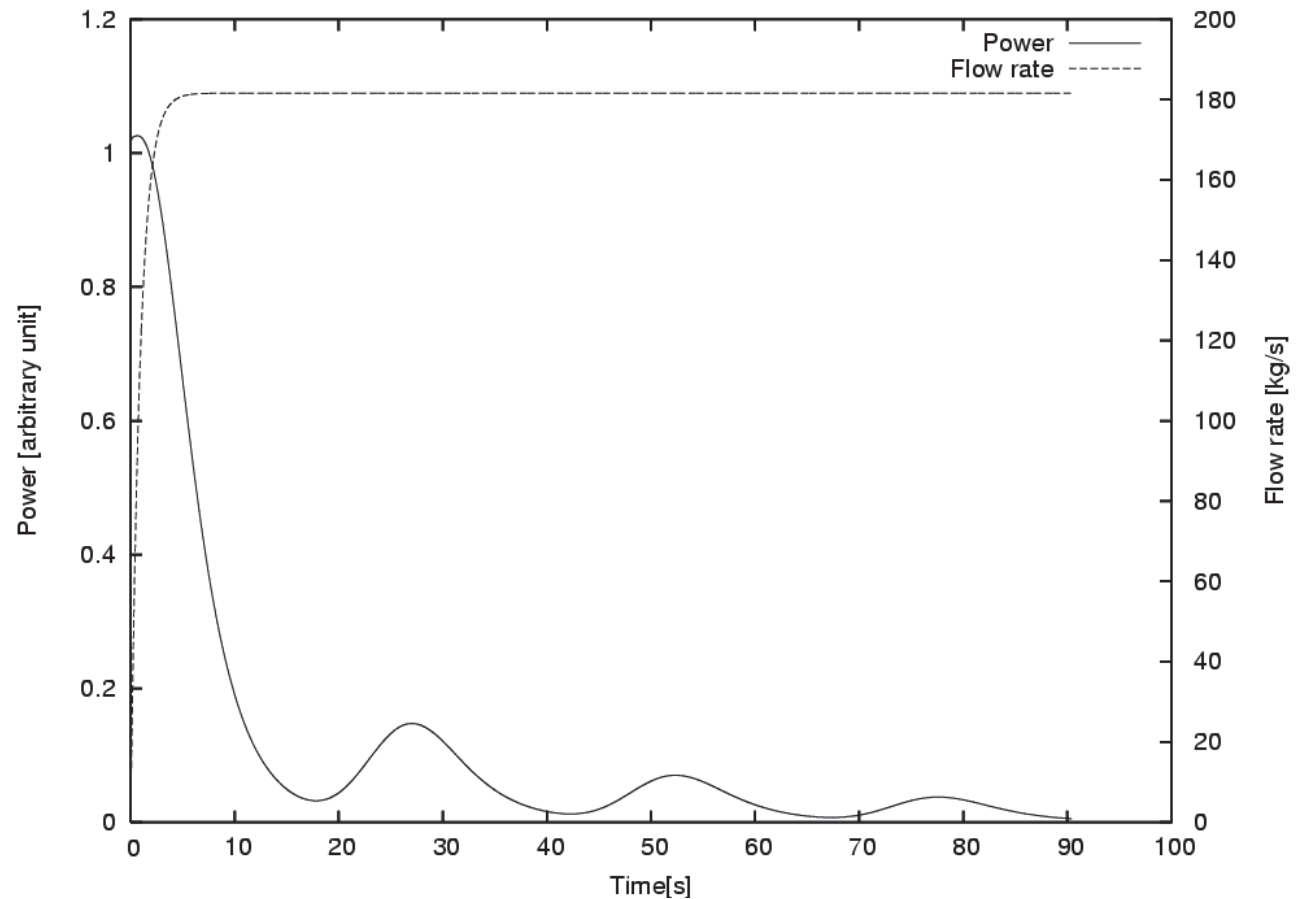
MSRE: Dynamic coupling

- ▶ Explicit scheme
- ▶ Exchange of power and temperature
- ▶ THERM and DALTON calculate each step separately
- ▶ Communicate afterwards

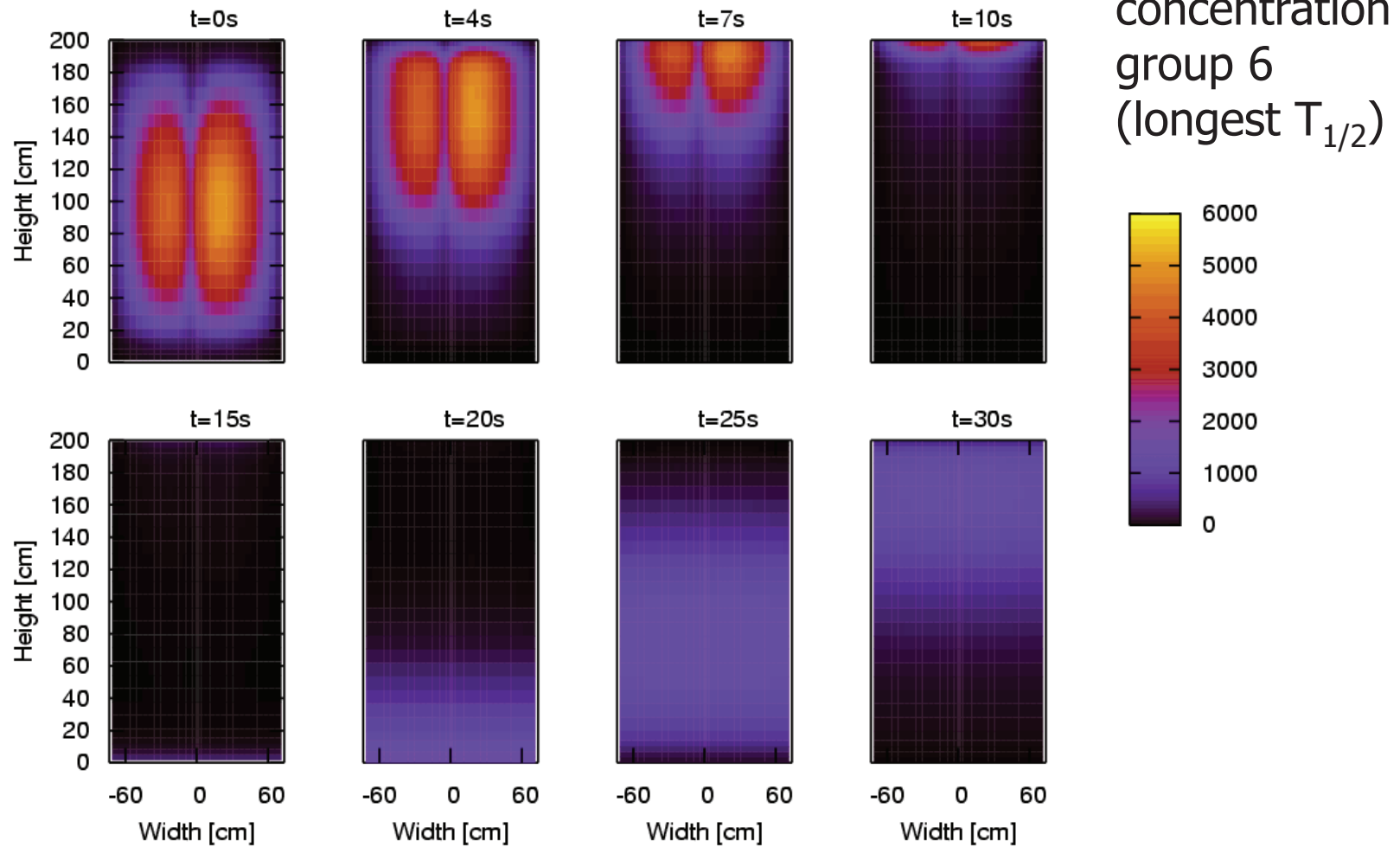


MSRE: Pump start-up

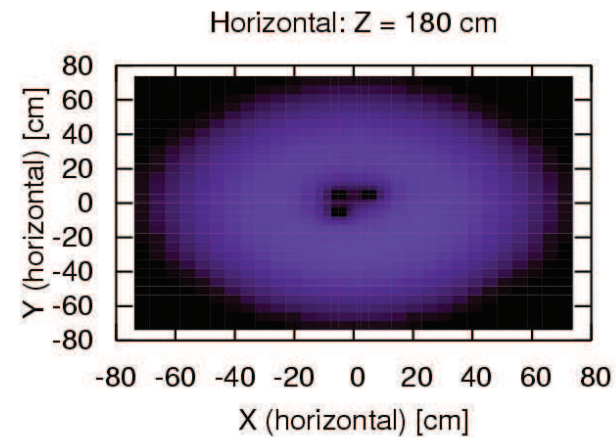
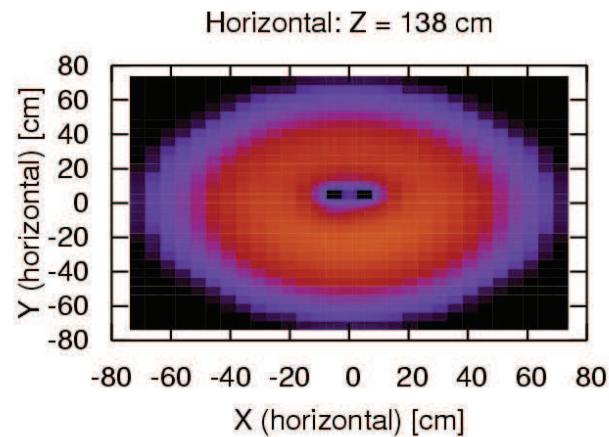
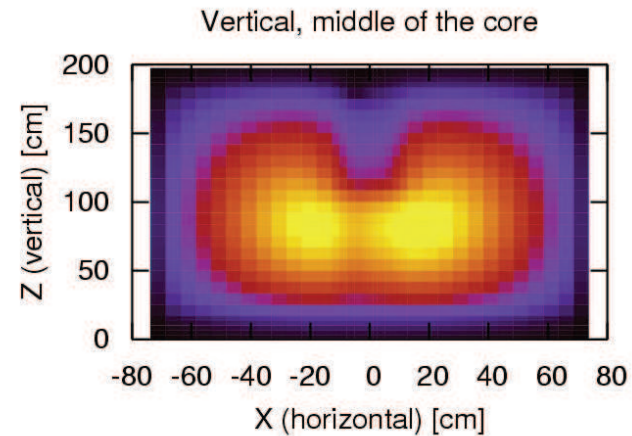
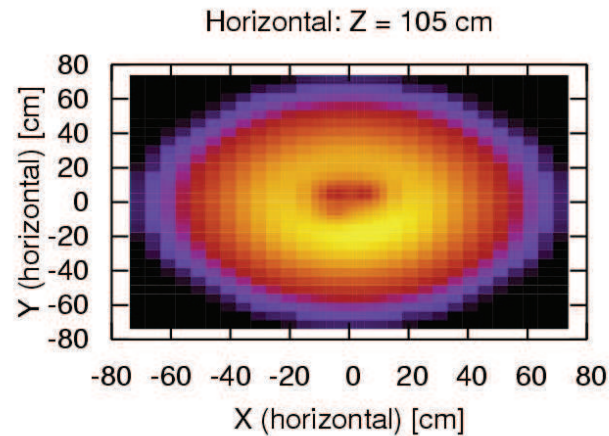
- ▶ Typical fluid-fuel transient
- ▶ Power: 1W
no feedback
- ▶ Beginning:
 - fuel stationary
 - $k_{\text{eff}} = 1$
- ▶ Starting fuel pump



MSRE: Pump start-up

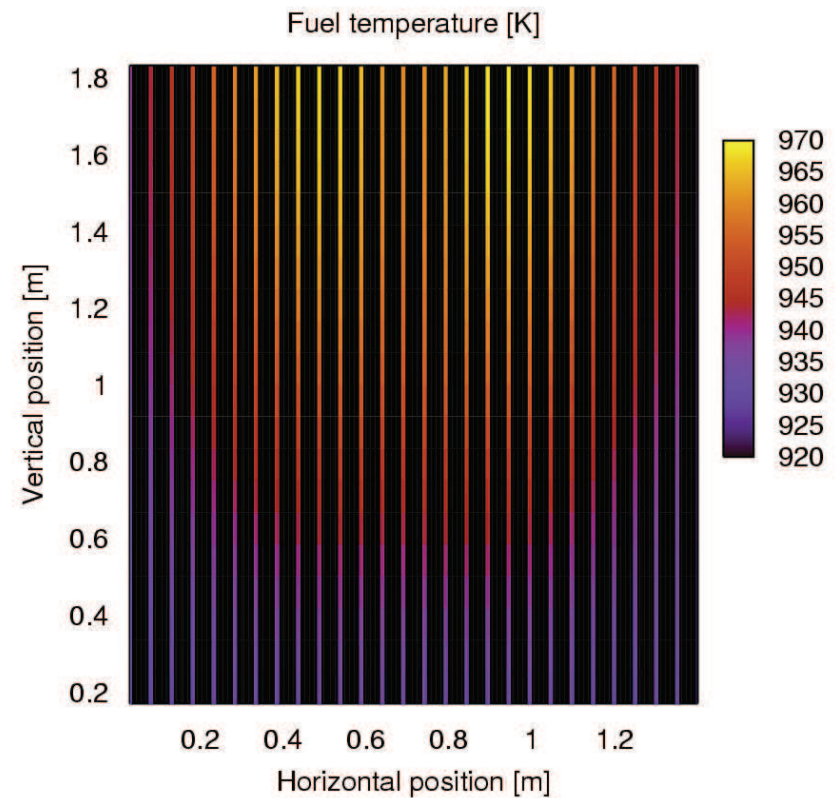
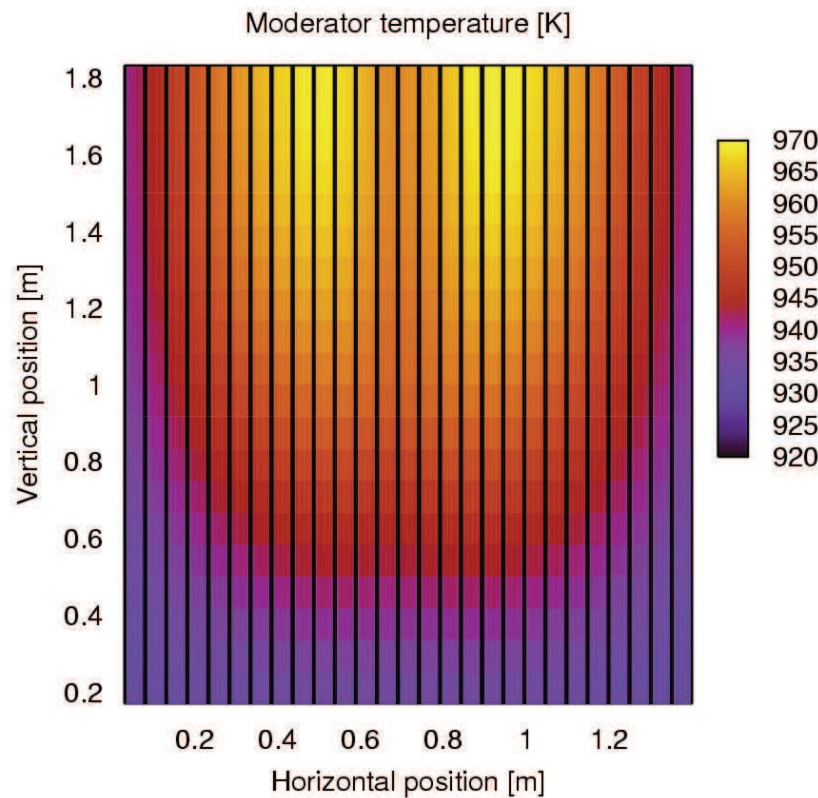


MSRE: Thermal flux (static)



power 8.59 MW

MSRE: Temperature (static)

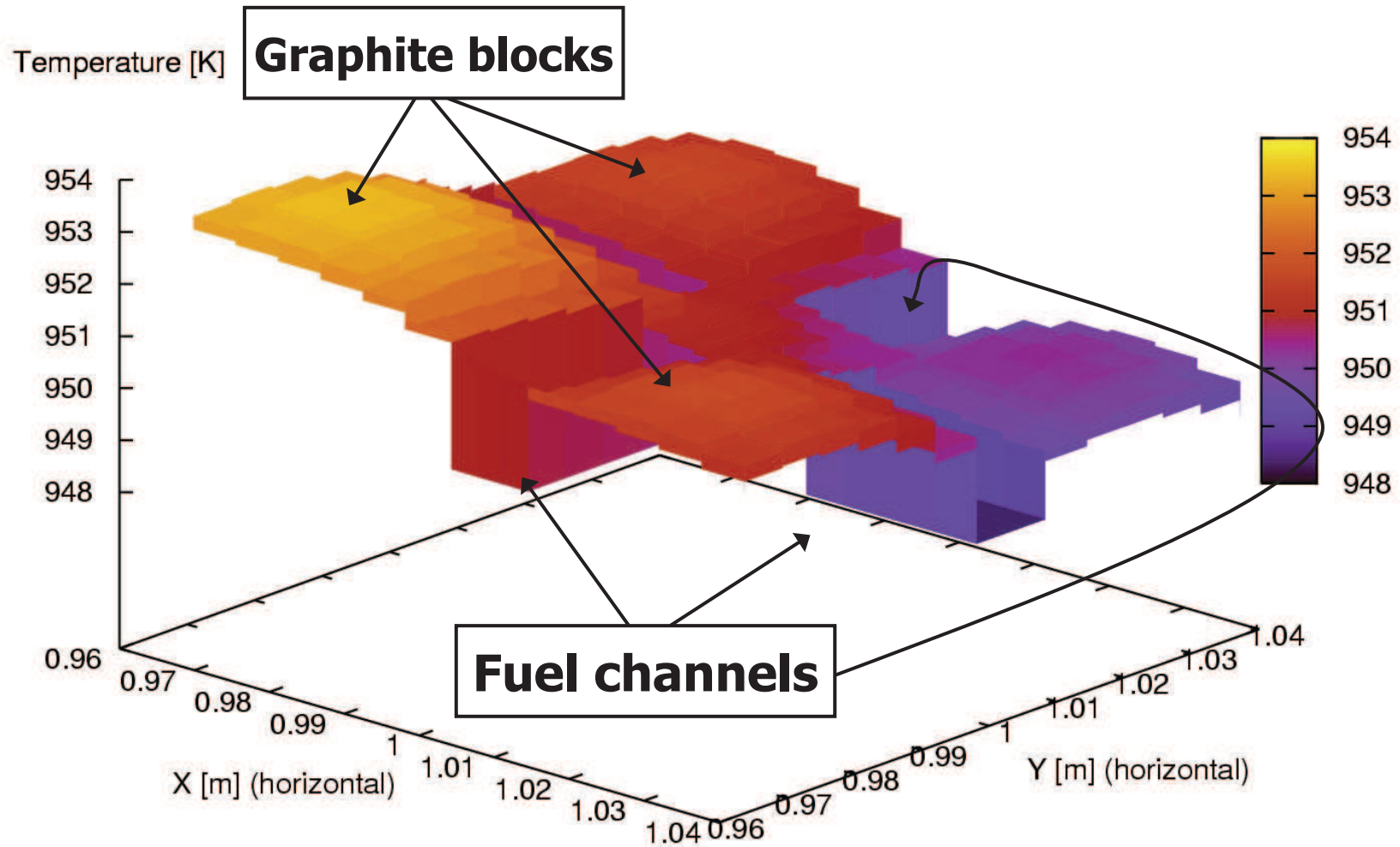


power 8.59 MW



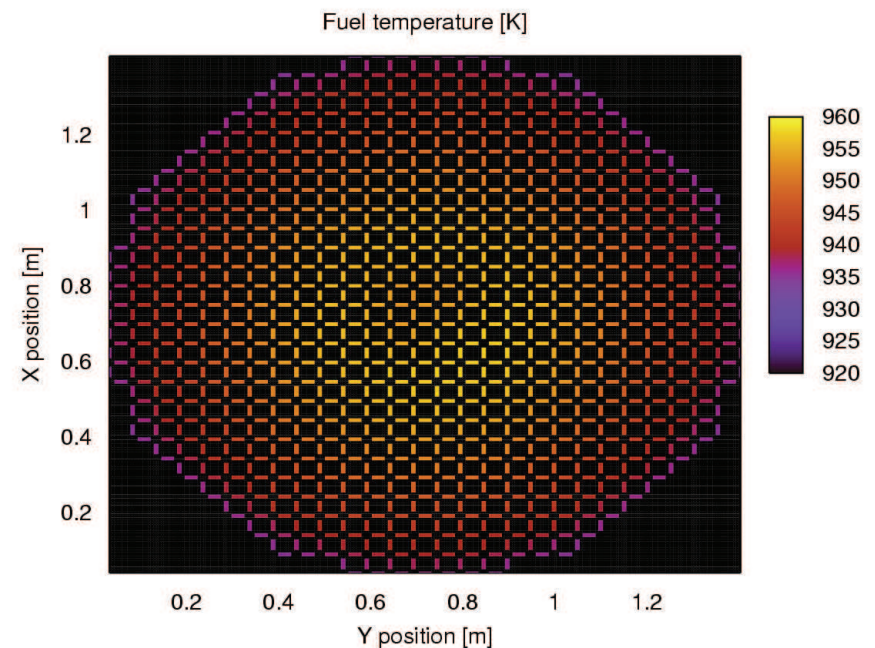
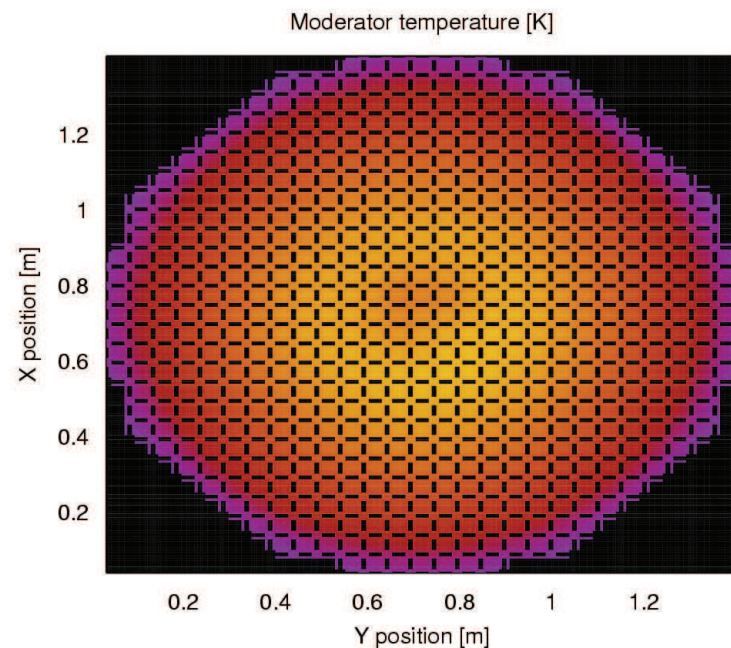
MSRE: Temperature field close-up

High resolution calculation to determine the surface temperature of the graphite and the heat transfer



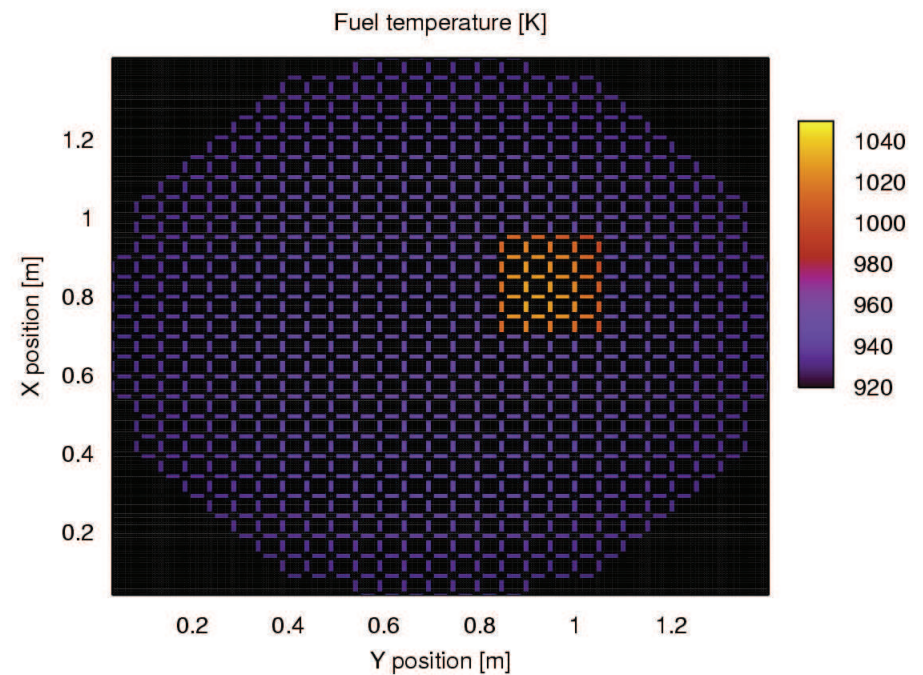
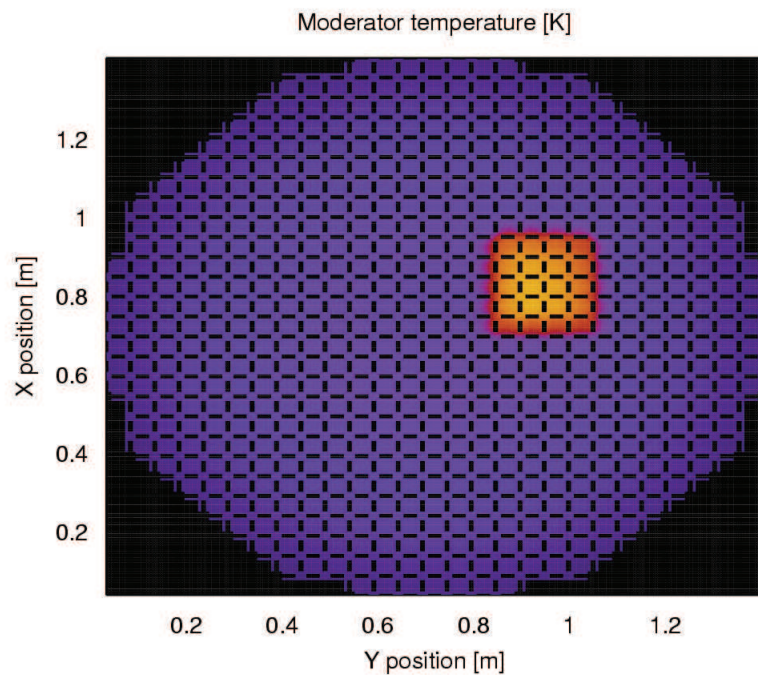
MSRE: Temperature field (static)

Horizontal cross-sectional of temperature fields at the middle of the core



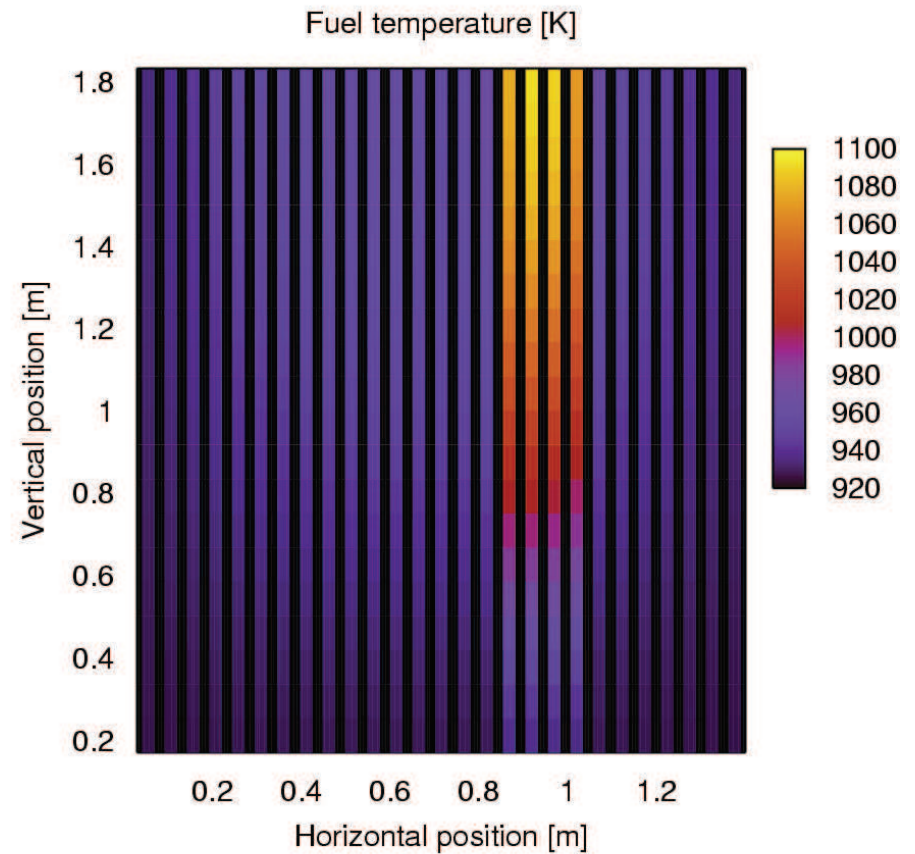
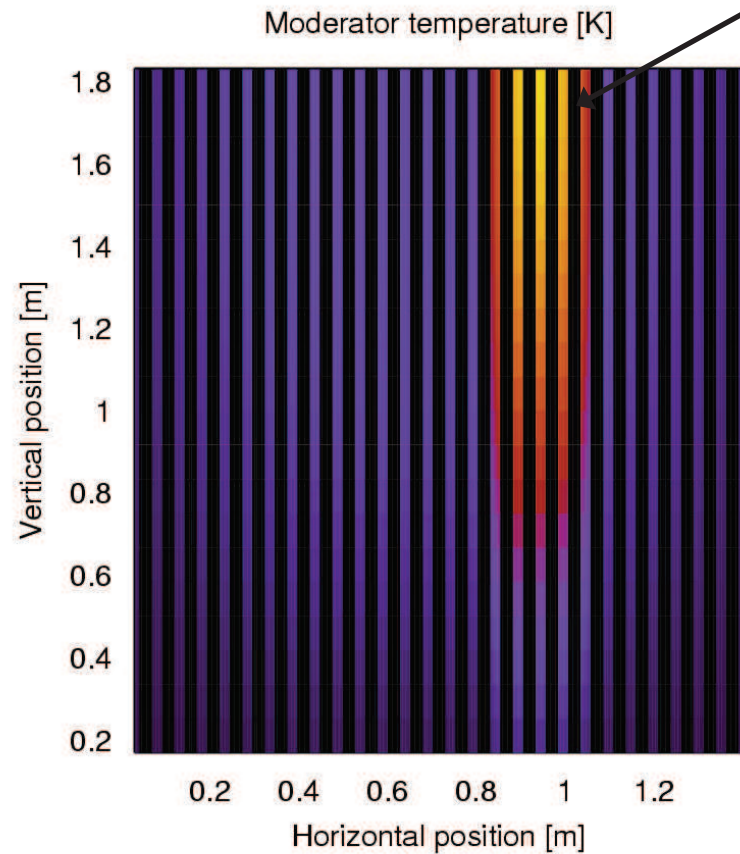
MSRE: Debris accident

- ▶ Debris gets into primary loop
- ▶ Blocks some of the fuel channels – mass flow reduced by 80%
- ▶ Total mass flow maintained
- ▶ Power reduces: 8.59 MW → 8.32 MW

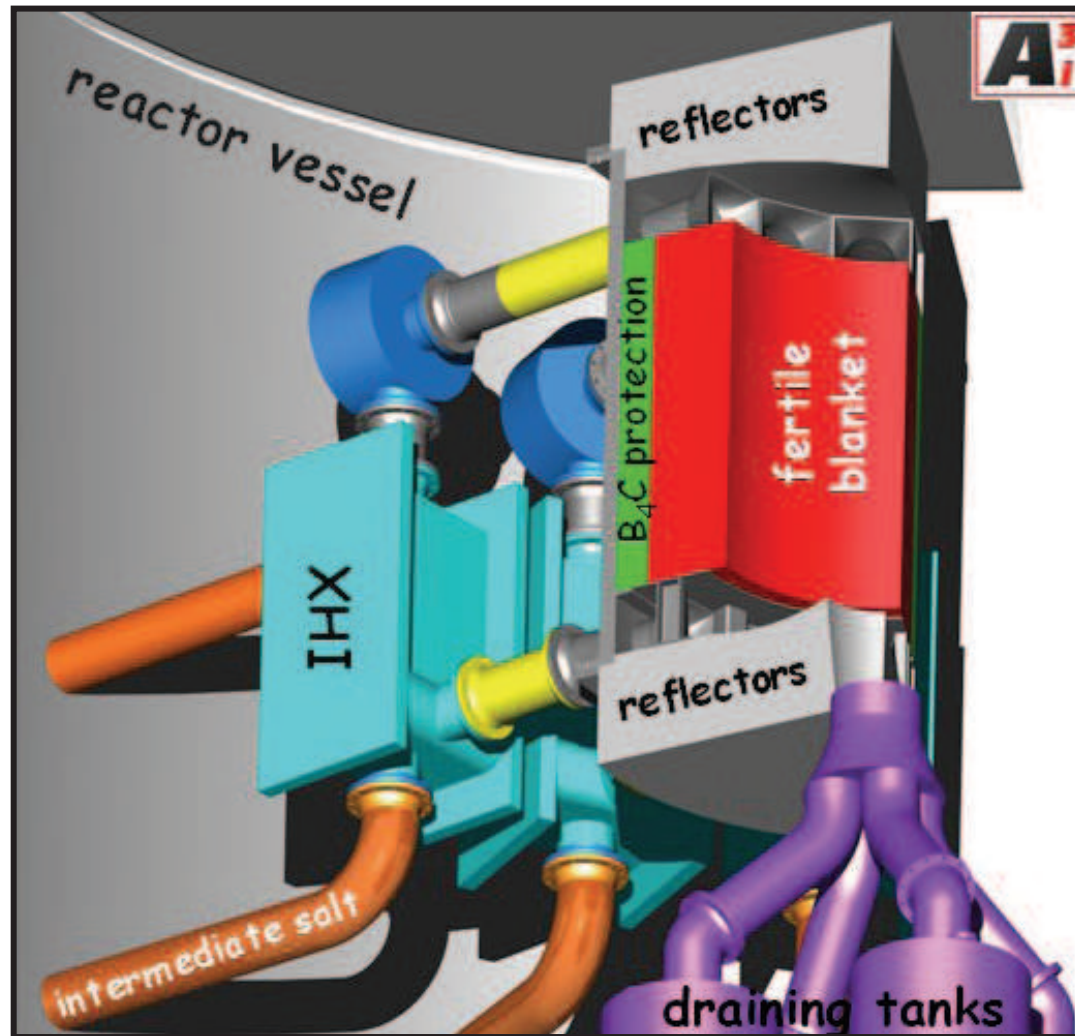


MSRE: Debris accident

Graphite conducts the heat from blocked channels

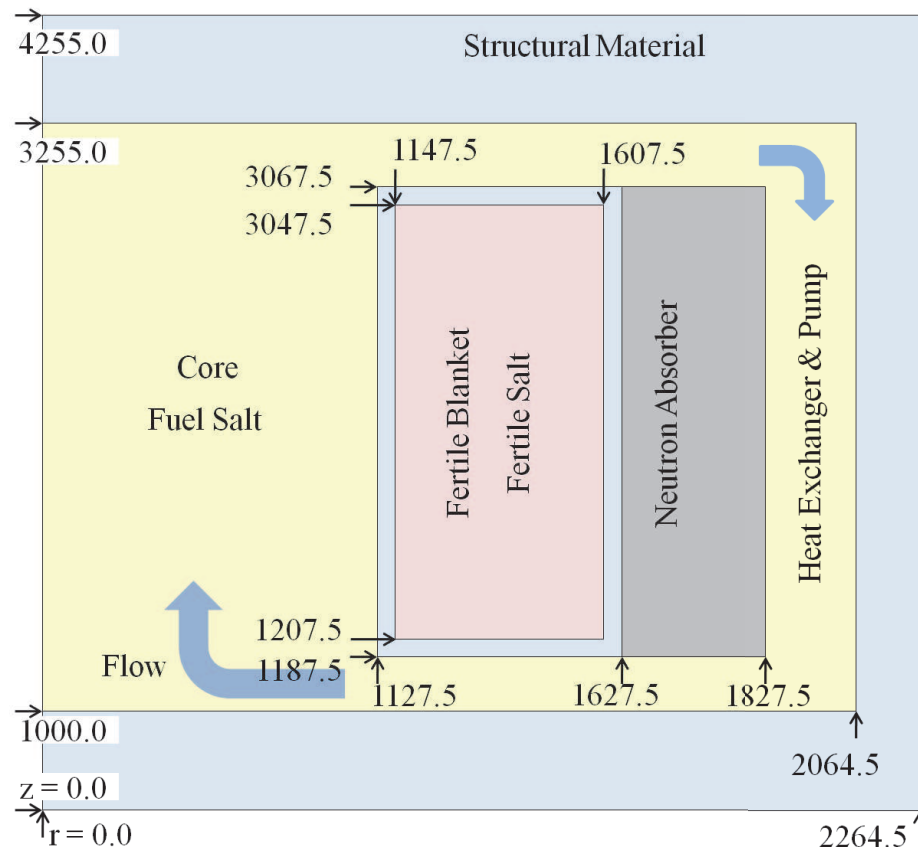


Molten Salt Fast Reactor (EVOL project)



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MSFR: Geometry and physics



Modeling:

- No heat transfer in blanket, reflectors and absorber regions
- Fresh fuel
- No flow in blanket
- Complete rz models for neutronics and heat transfer and fluid dynamics
- Properties from benchmark description (except 'Boussinesq' and some simplified materials)

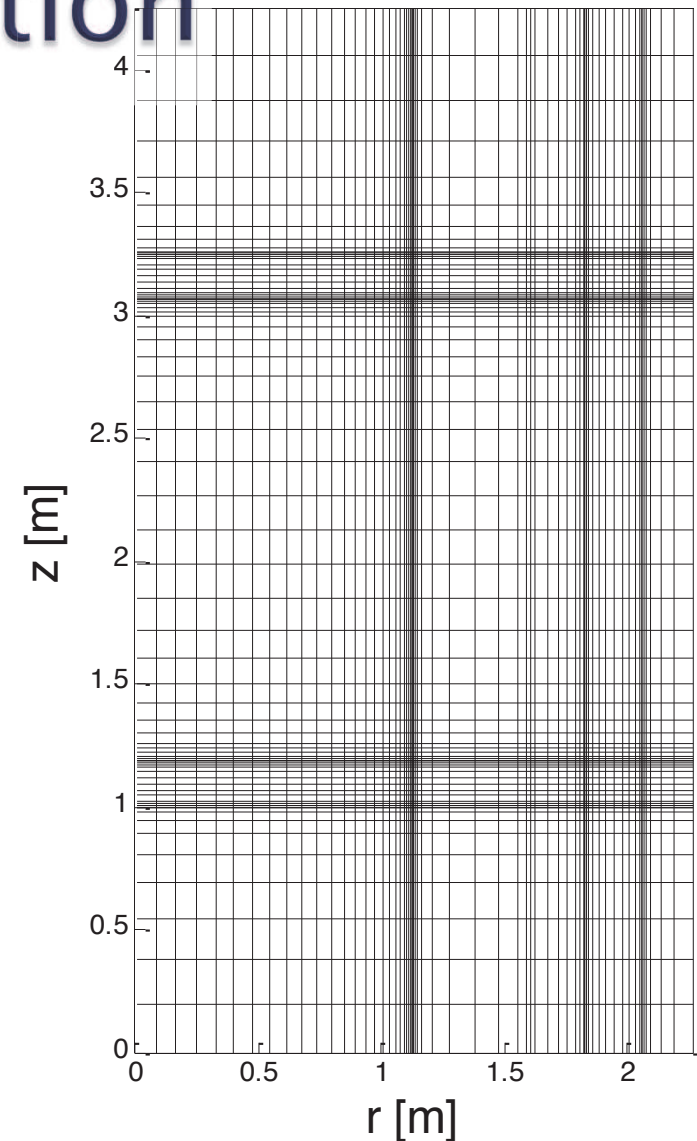
MSFR: Mesh generation

Computational mesh for neutronics 66x78

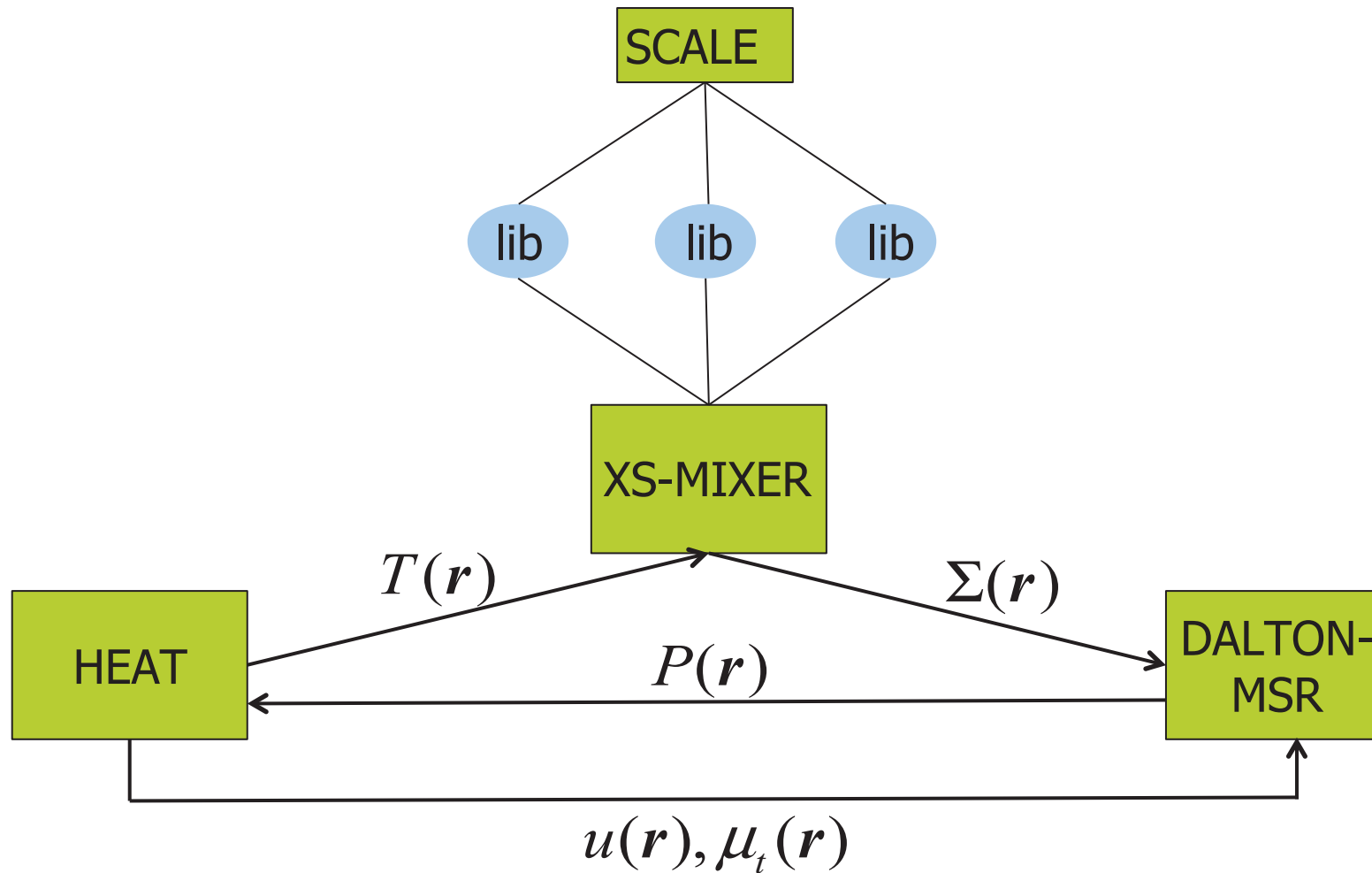
CFD mesh twice as fine in each direction (132x156). Has proper width near walls for correct behavior of turbulence model, i.e. y^+ values (friction, turbulence)

Meshes overlap for simplicity where CFD dictates refinement near walls

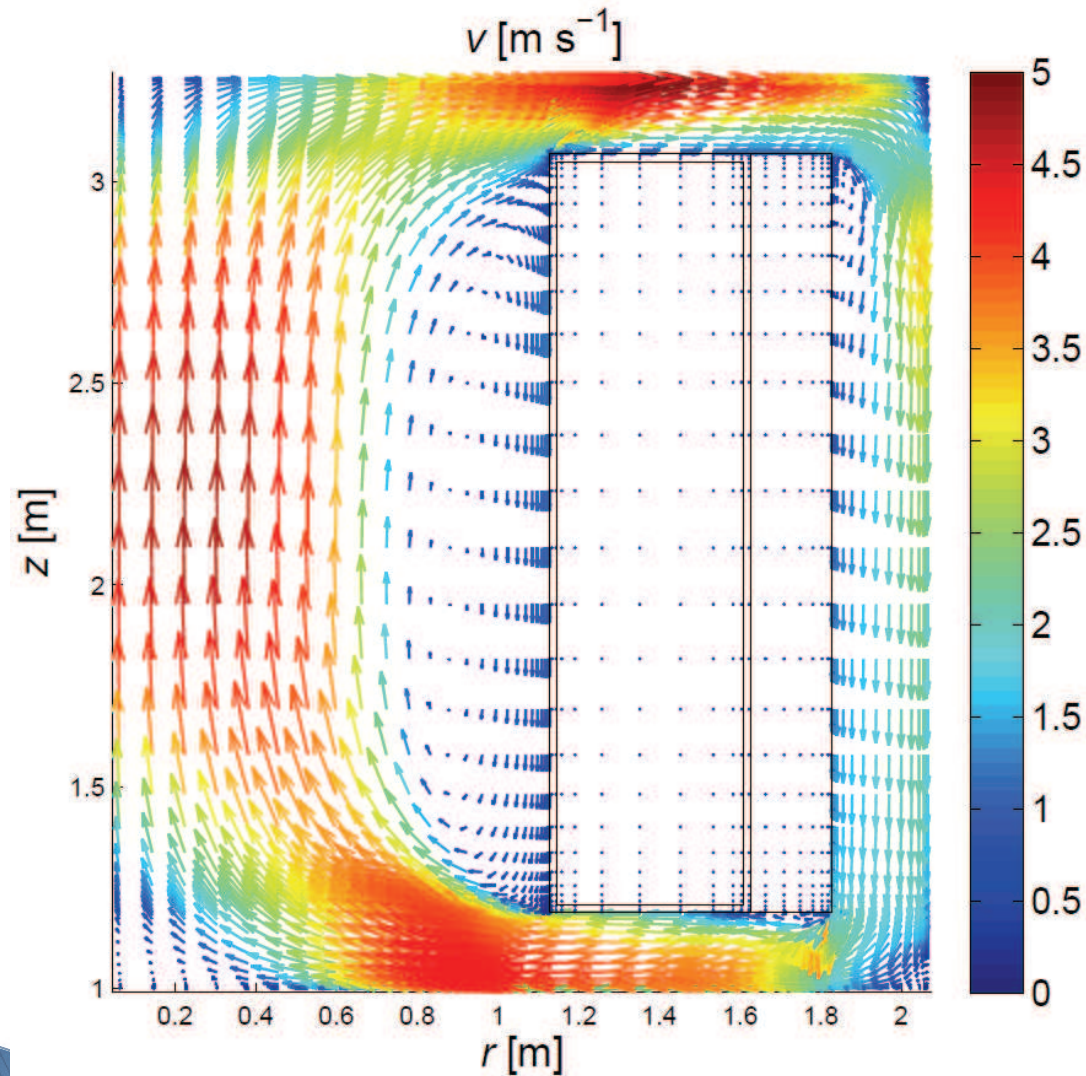
Interpolations required for data transfer between codes (conservation issue)



MSFR: Computational scheme

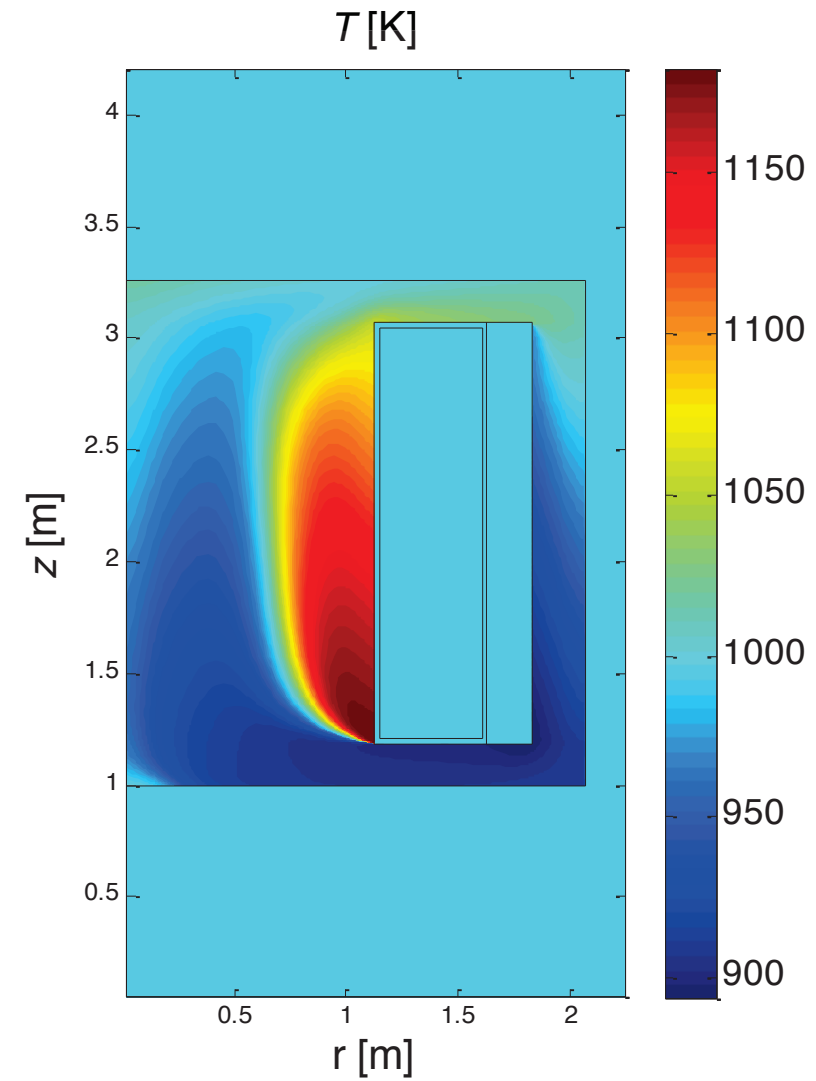
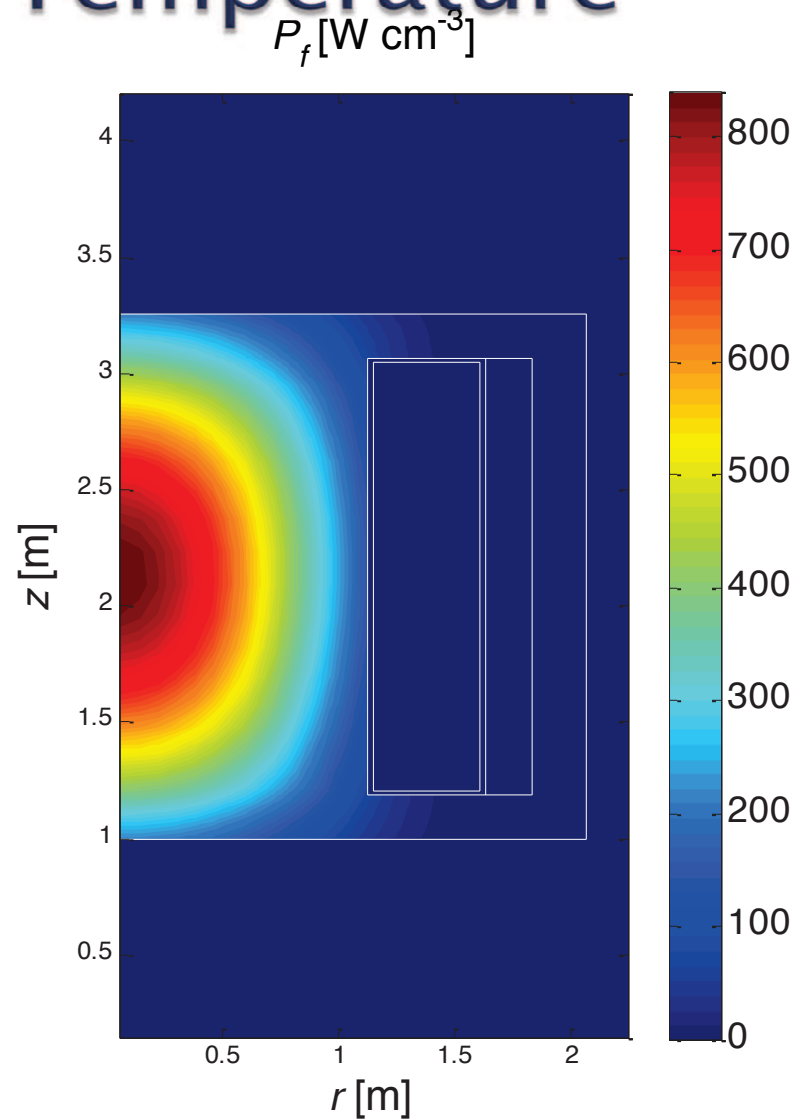


MSFR: Steady state, mean flow

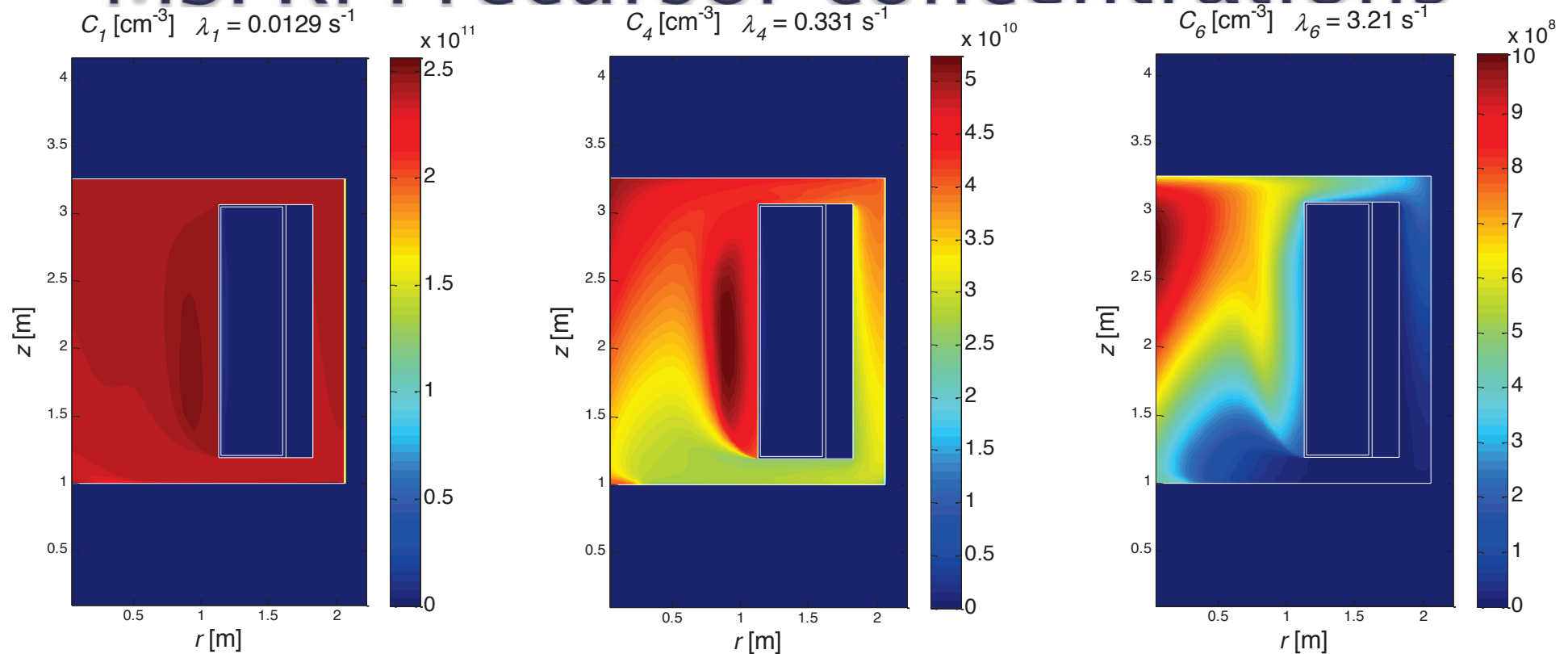


- Main recirculation loop: disadvantage for temperature field
- Small secondary flow in corner regions

MSFR: Steady state, Power density, Temperature

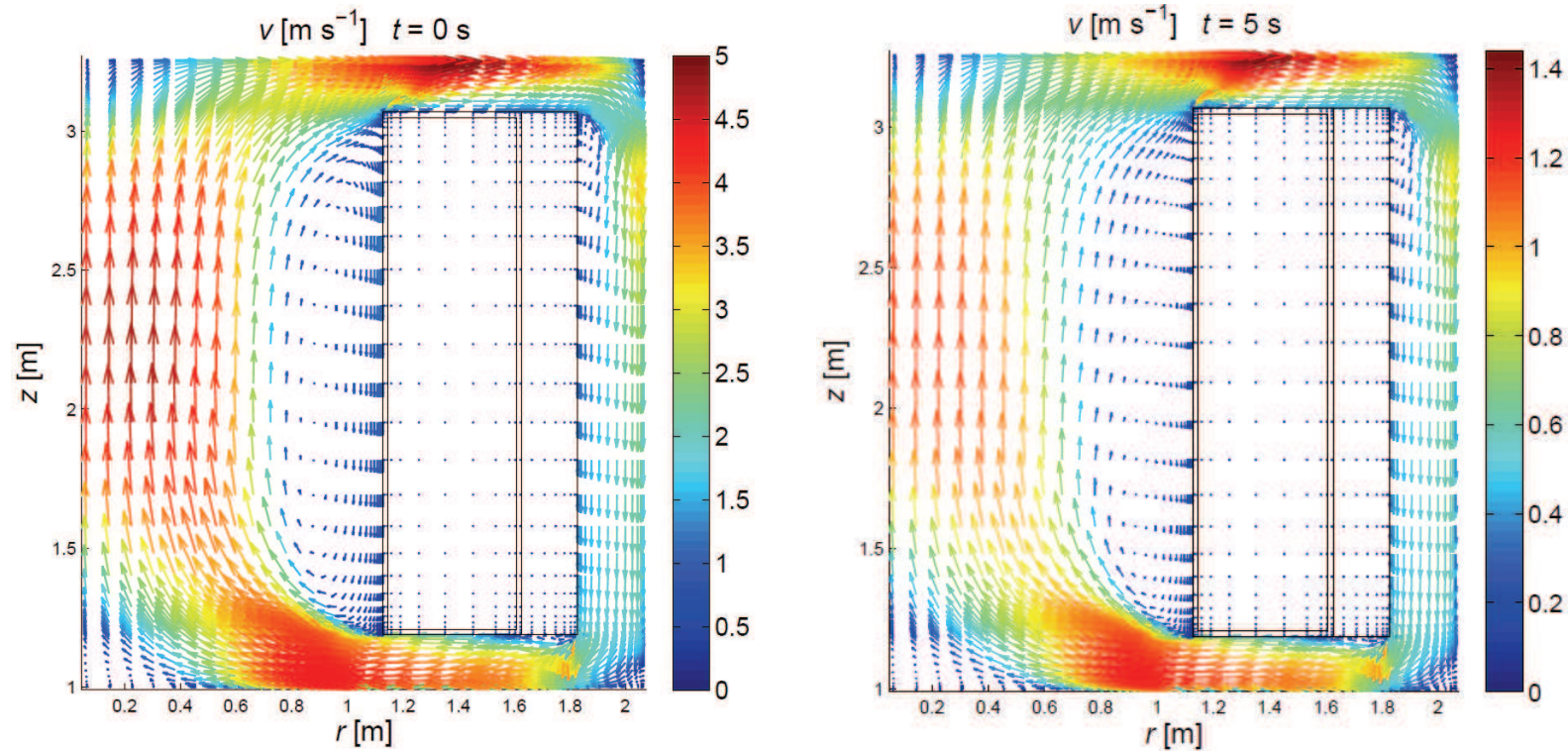


MSFR: Precursor concentrations



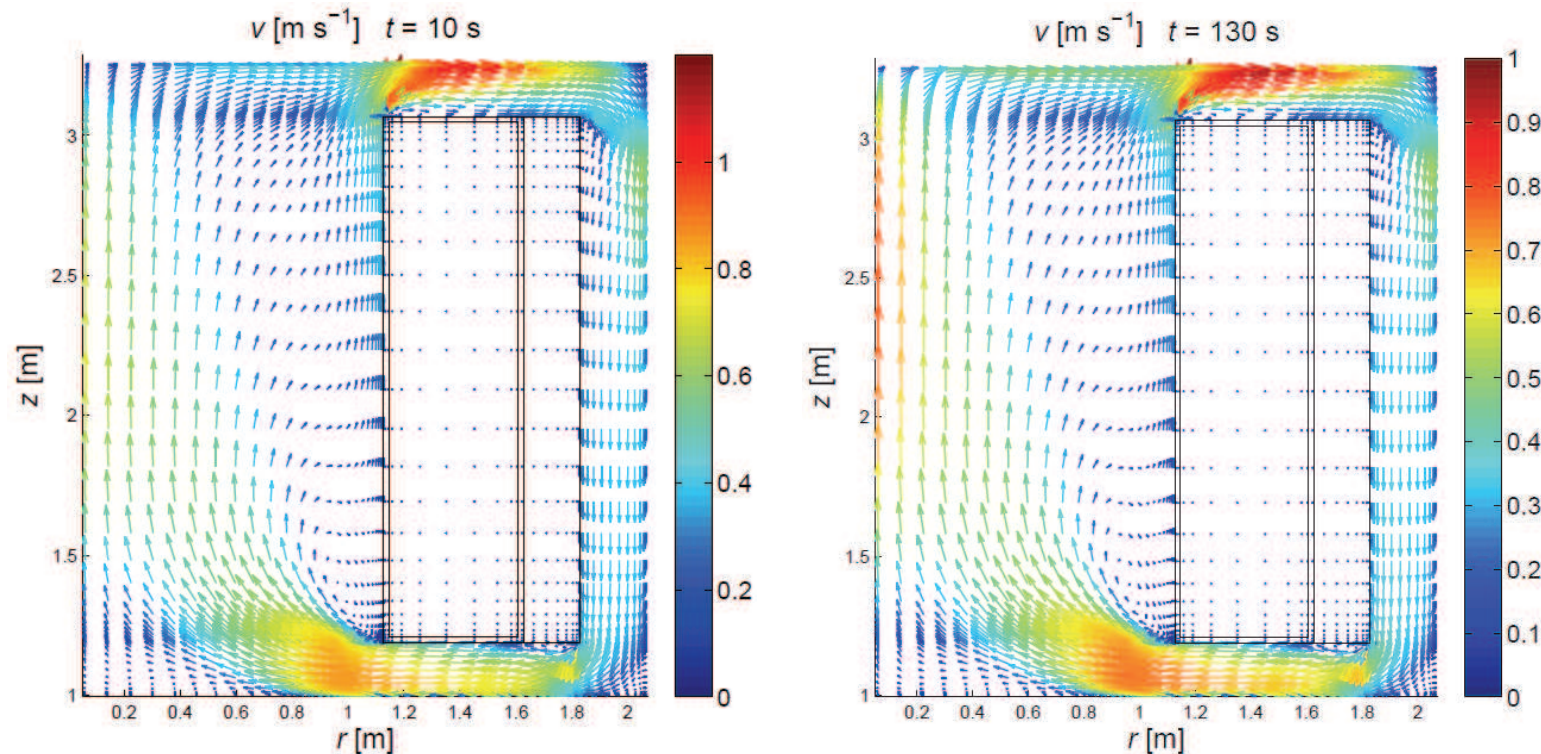
- Long lifetimes: homogeneous distributions and decay.
- Short lifetimes: local balance between production and decay. Only slight shift in spatial distribution. Complete decay in down comer.
- Intermediate lifetimes: mixed ...

MSFR: Pump failure



- Rapid initial decay of flow rate within first 5 seconds

MSFR: Pump failure



- Flow almost steady state after 130 seconds
- Flow rate decreased by factor 6 compared to steady-state
- Pure natural convection with different structure of recirculation zone
- Complex interplay between flow and buoyancy

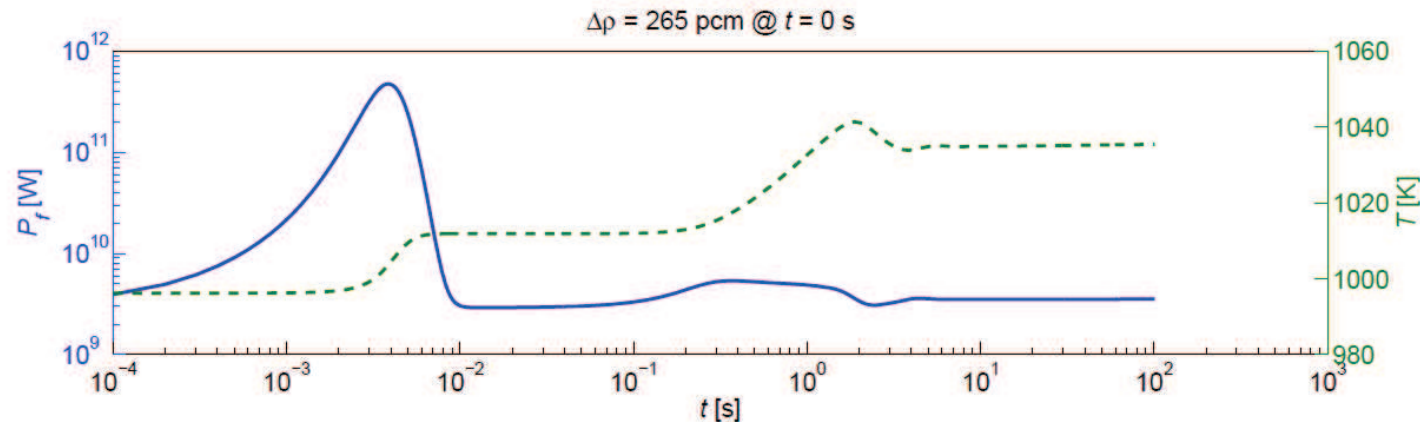
MSFR: Reactivity insertion

Sequence of events

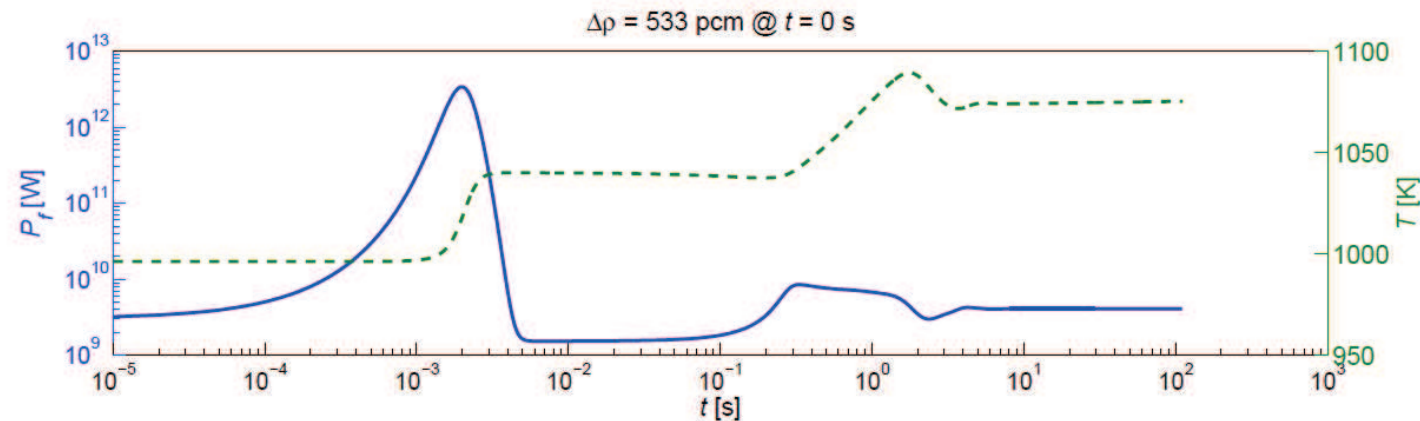
- Reactivity is instantaneously added by increasing U-233 density
- 'Prompt jump' occurs, where feedback limits the growth
- Delayed effects from precursors
- Complex interplay of hot and cold fluid exiting and entering the core region cause some further transients until final steady state is reached
- The final power in steady state is slightly larger than the initial power to compensate for the external reactivity



MSFR: Reactivity insertion



(d) For the new steady state $P_f = 3.5 \text{ GW}$ and $T = 1035 \text{ K}$.



(e) For the new steady state $P_f = 4.1 \text{ GW}$ and $T = 1075 \text{ K}$.

Conclusions on multi-physics modeling

- ▶ High-fidelity code systems are available for MSR systems (Delft, Milan, PSI, CNRS, KIT, etc)
- ▶ Realism of the simulations is continuously increasing (geometric complexity, physics)
- ▶ Indispensable tool for safety analysis of MSR
- ▶ Still immense computational problem
- ▶ Future holds more
 - Chemistry coupling
 - Structural analysis
 - ...



Some of our publications on MSR

- ▶ J. Kophazi et al. Development of a three-dimensional time-dependent calculation scheme for molten salt reactors and validation of the measurement data of the molten salt reactor experiment Nucl. Sci. Eng 163(2), pp 118–131, 2009.
- ▶ C. Fiorina et al. Modeling and analysis of the MSFR transient behaviour. Annals of Nucl. Energy 264 (485–498), 2014.
- ▶ K. Nagy. Dynamics and fuel cycle analysis of a moderated molten salt reactor. PhD thesis. + his papers
- ▶ Master theses Michiel Hoogmoed, Erik van der Linden, Lodewijk Frima.
- ▶ Downloads at <https://www.tudelft.nl/en/faculty-of-applied-sciences/about-faculty/departments/radiation-science-technology/kloosterman-group/publications/>



